

# An Investigation of Generic Approaches to LNS

Filipe Souza, Dr. Diarmuid Grimes, Dr. Barry O'Sullivan

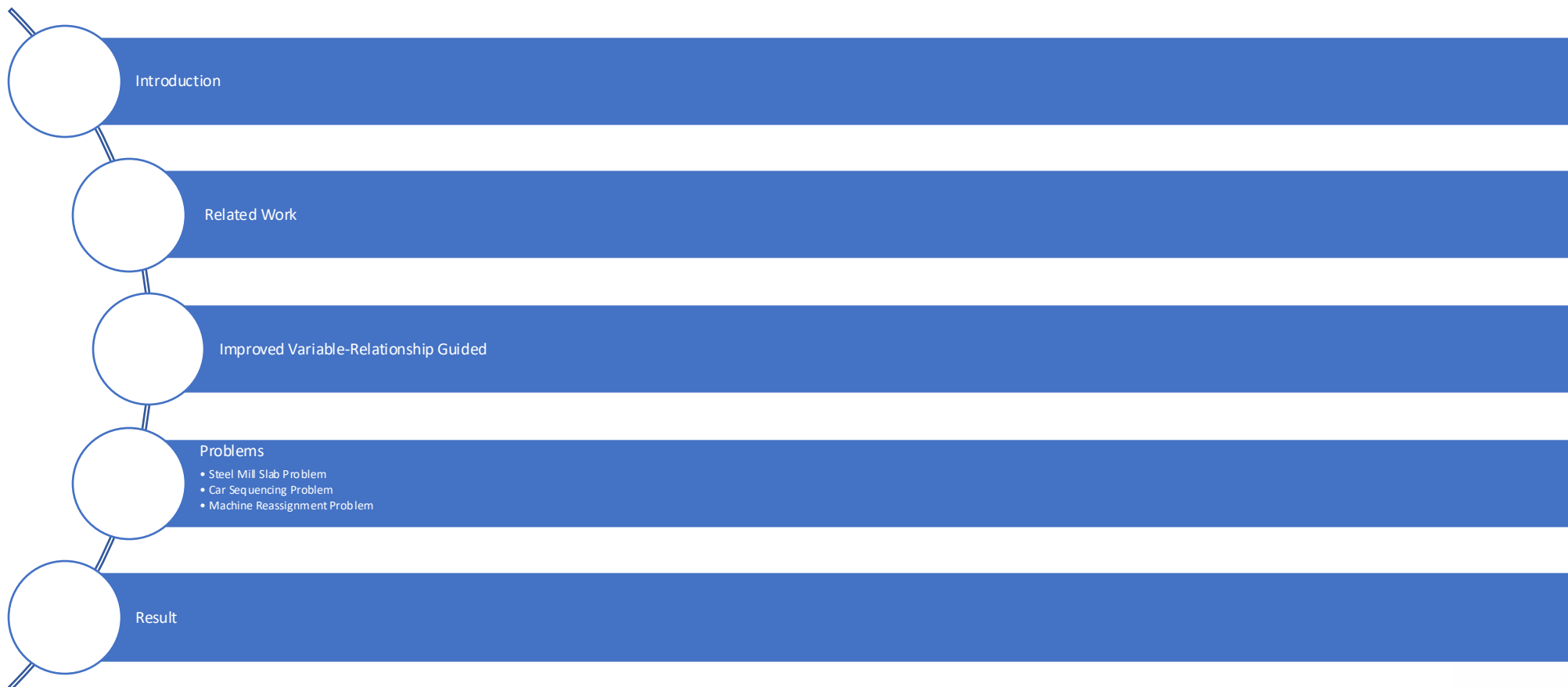
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# Introduction

Large Neighbourhood Search (LNS) has been demonstrated to be extremely powerful approach in numerous application types

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# Introduction

Large Neighbourhood Search (LNS) has been demonstrated to be extremely powerful approach in numerous application types

- Success often depends on experts designing **domain-specific** heuristics for **neighbourhood selection**
- **Heuristics** are often not easily **transferable** between **domains**.

While **systematic search** offers strong **generic heuristics** (e.g., weighted degree, impact-based, activity-based) for **plug-and-play** without **domain-specific** knowledge.

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The goal of our work was to develop a **generic neighbourhood selection operator** that performs well across multiple problem types

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# *What makes a good neighbourhood operator?*

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# *What makes a good neighbourhood operator?*

First let's flip this question and consider what is a **bad neighbourhood**:

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# *What makes a good neighbourhood operator?*

First let's flip this question and consider what is a **bad neighbourhood**:

- **No Search Space:**
  - **Domains** of relaxed variables are **reduced** to their **solution values** after **propagation**.
  - Limited scope for improvement.
- **Too Much Search Space:**
  - **No propagation** effects from assignments.
  - Search space is **vast** and **disconnected**.
  - Leads to **brute-force** search over every **domain value**, inefficient and time-consuming.

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# *what makes a good neighbourhood operator?*

First let's flip this question and consider what is a **bad neighbourhood**:

## What we want in a neighbourhood:

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**What we want in a neighbourhood:**

- **Scope for Improvement:**
  - Uses variables **sharing constraints** to create **connected neighbourhood** that supports effective **propagation**.
  - Enables **efficient exploration** without excessive **domain reduction**.
  - Focuses on variables **likely to improve** the objective value.
- **Strong Diversification:**
  - Avoids **repetitive** selections to prevent **stagnation**.

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# Related Work

## Propagation Guided

- Proposed by Perron, Shaw and Furnon in 2004
- Uses **propagation information** to identify strongly **connected neighbourhood**
- The authors found **interleaving** the following three neighbourhood **heuristics** to work best:
  - **PG-LNS**: Start with **all variables unassigned**, and iteratively **freezes variables** until neighbourhood size
  - **Reverse PG-LNS**: Start with **all variables fixed**, and progressively **relaxes variables** until neighbourhood size
  - **Pure random**

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## Cost Impact Guided

- Proposed by Lombardi and Schaus in 2014
- Selects variables for relaxation based on their **impact on the cost**
- The cost impact is determined by the **variations** in the **lower bound** that occur when each **variable** is **assigned** a value
- The variations are captured through the **dives** of the **current solution** in a **rearranged order**

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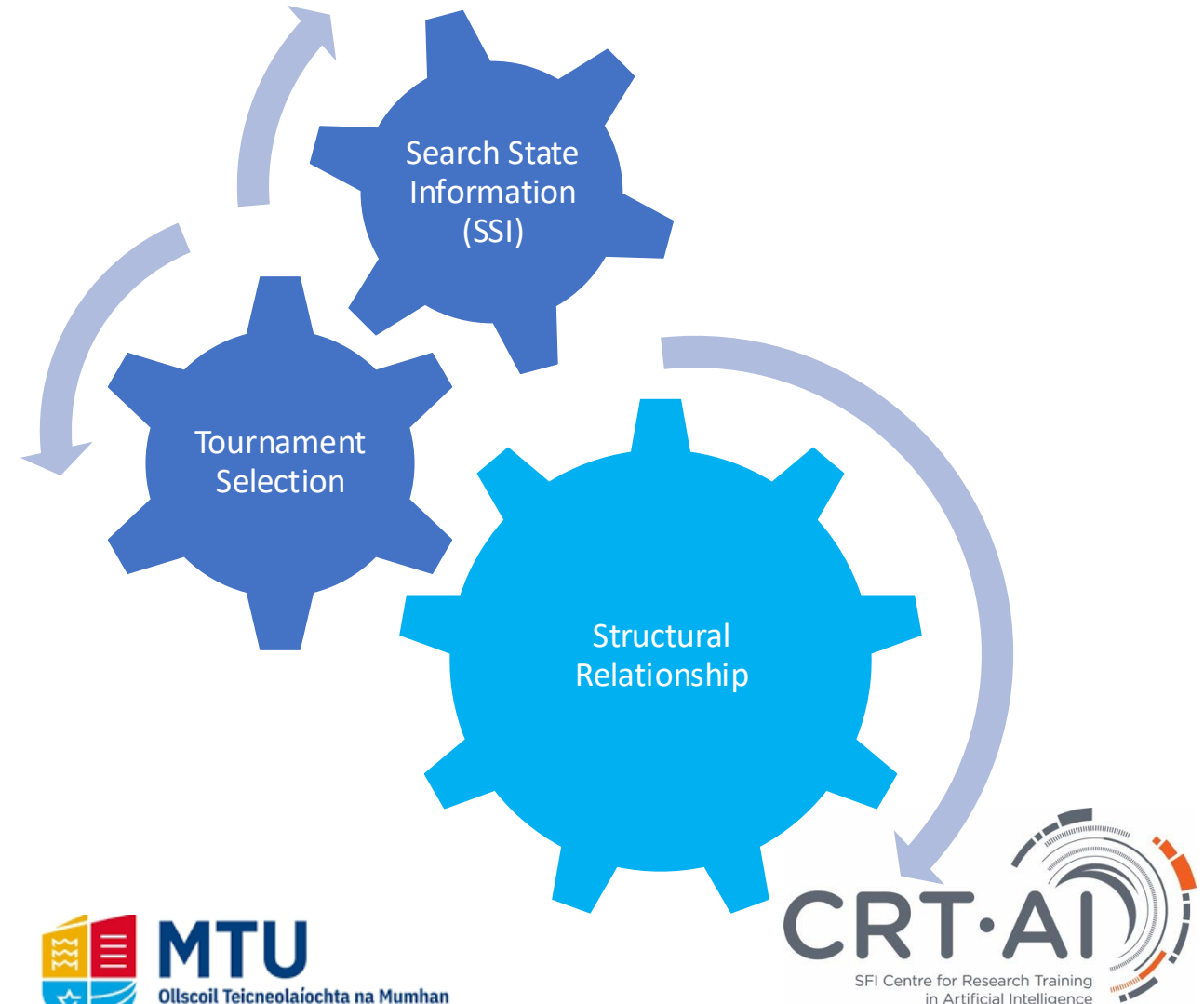


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# Improved Variable-Relationship Guided LNS

- Exploits the **structural relationship** between variables to guide the search process towards **connected neighbourhoods**



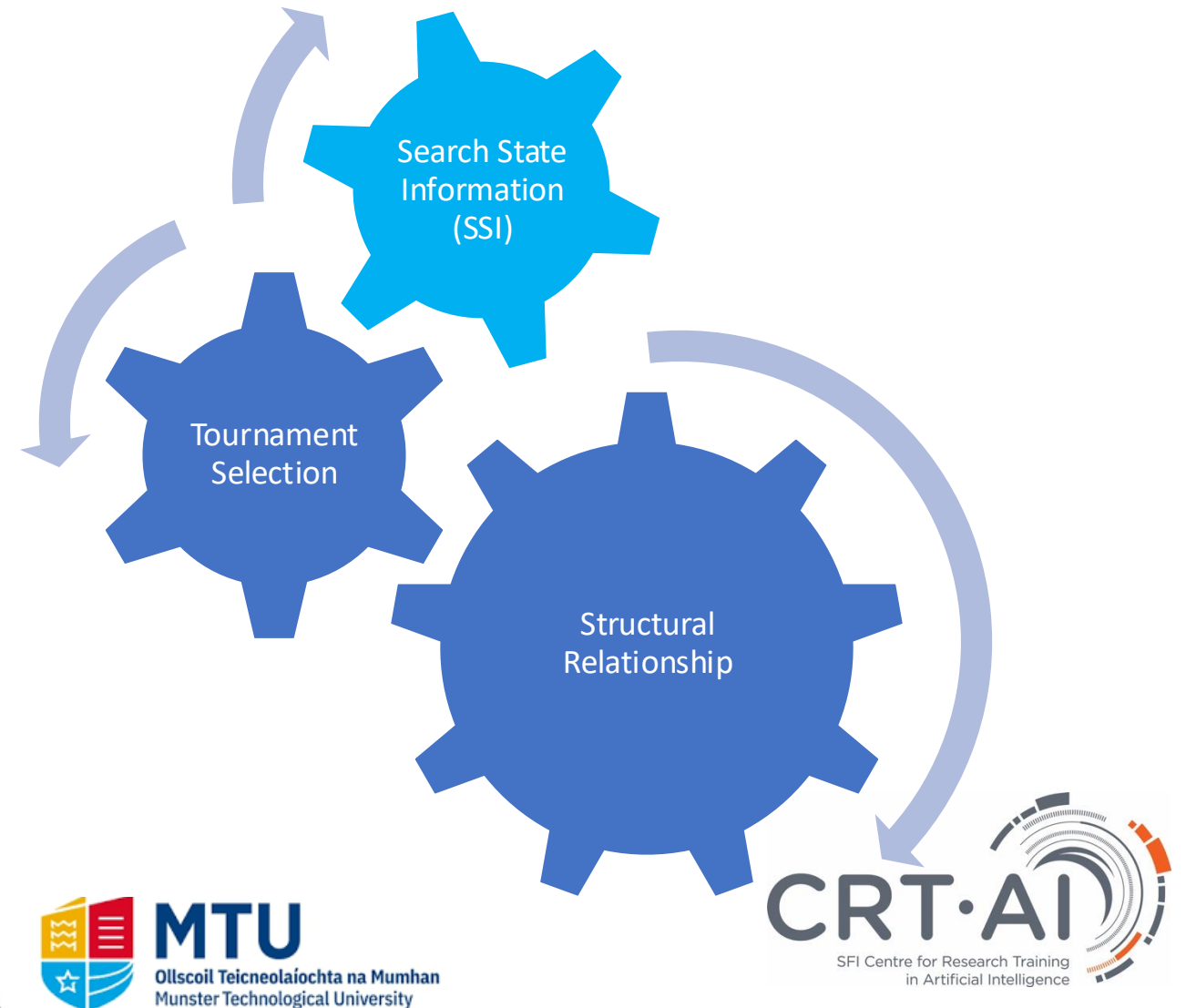
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# Improved Variable-Relationship Guided LNS

- Exploits the **structural relationship** between variables to guide the search process towards **connected neighbourhoods**
- Combines it with **dynamic information** that describes the **variables states** along search

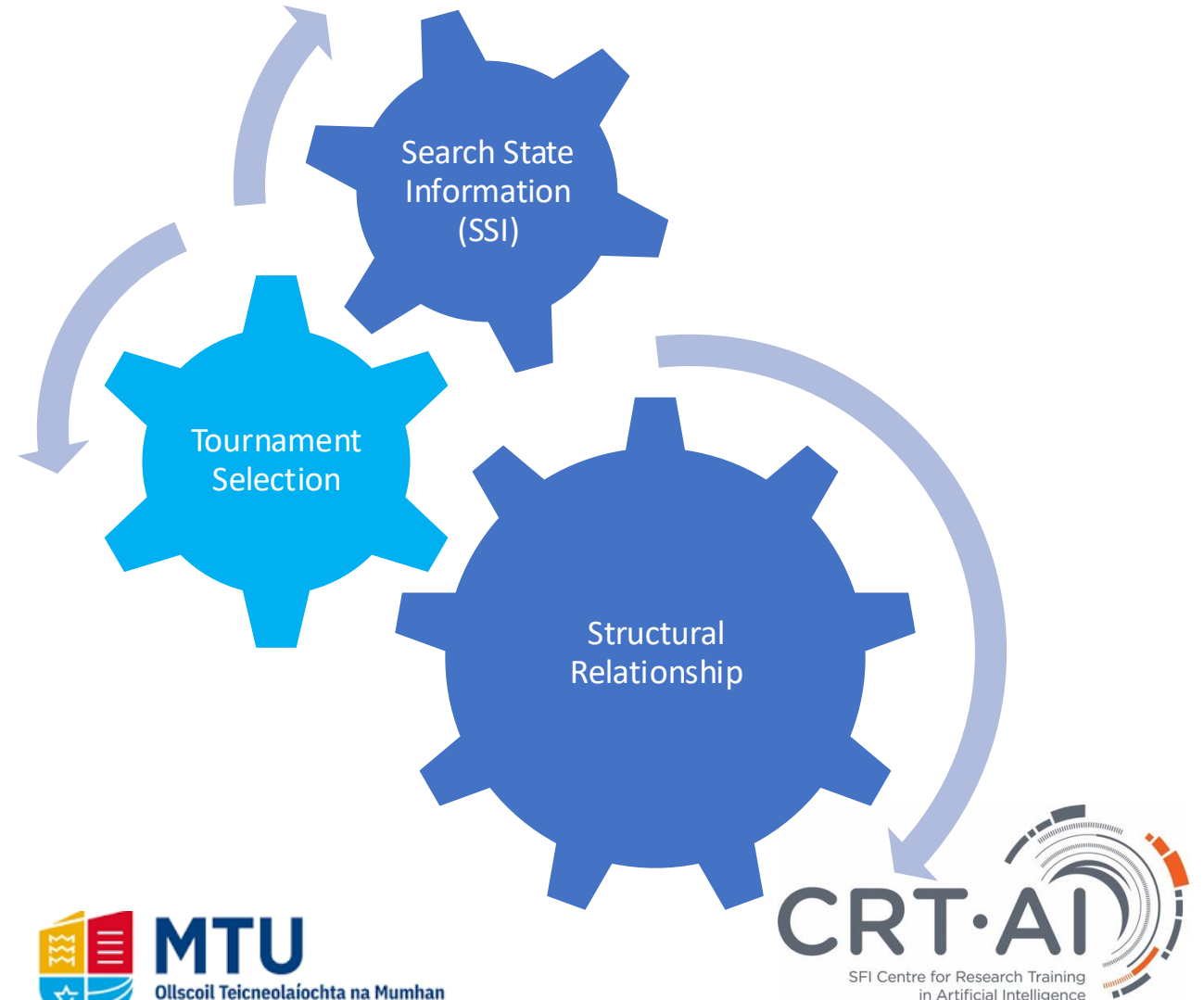


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# Improved Variable-Relationship Guided LNS

- Exploits the **structural relationship** between variables to guide the search process towards **connected neighbourhoods**
- Combines it with **dynamic information** that describes the **variables states** along search
- Uses **Tournament selection** to boost **diversification** and **reduces computational effort** by focusing on finding the best candidates from a subset, rather than from the entire set of variables.



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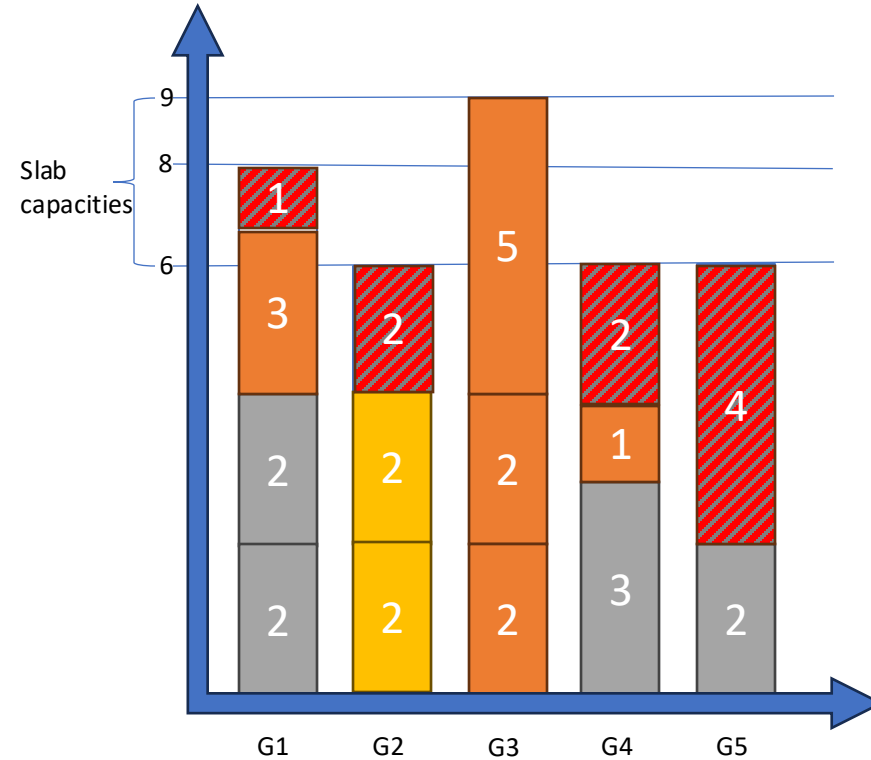
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# Steel Mill Slab Problem (SMSP)

- Involves to **assign steel orders to slabs** while **minimising slab wastage**
- Each **slab** has a **maximum weight capacity**
- **Orders** have specific **weight** and **colour**
- This problem was used in the original **Cost Impact Guided** paper

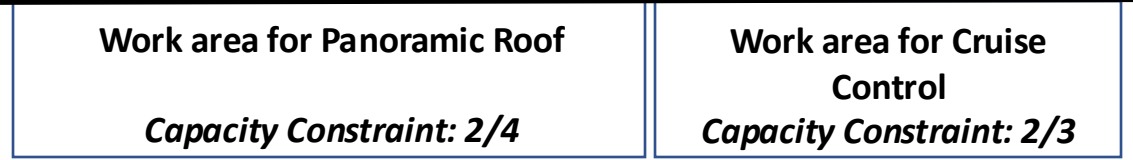


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# Car Sequencing Problem(CSP)



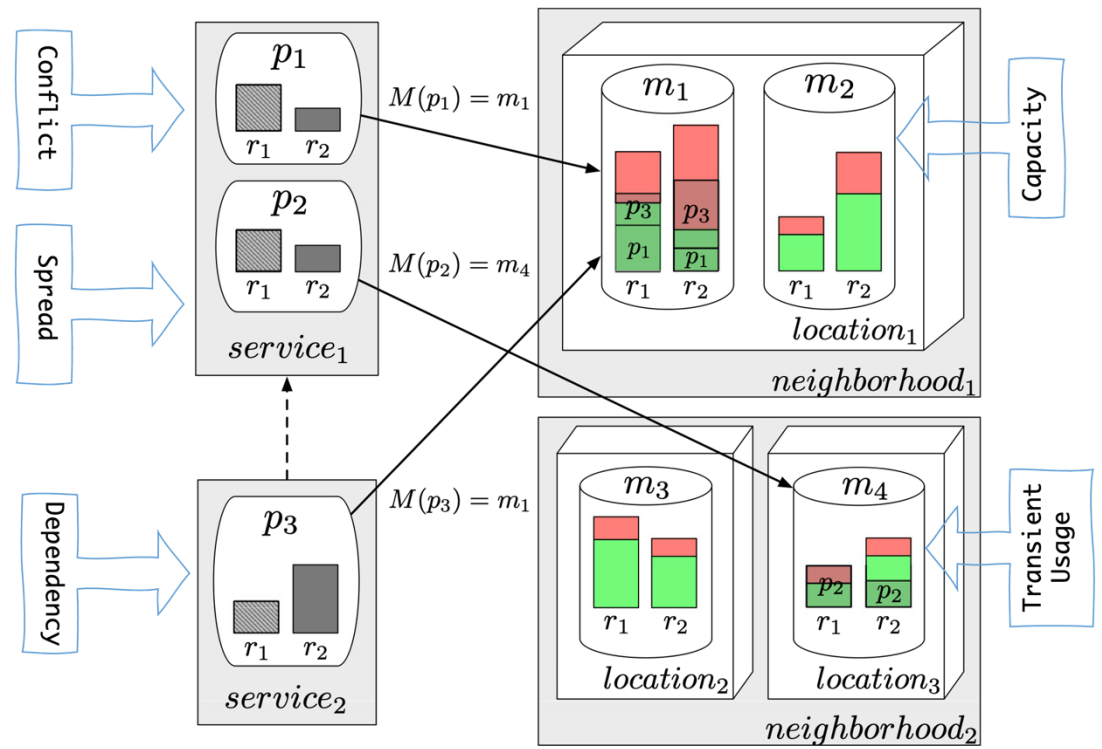
- **Allocates** a set of cars on a **production line** of options' installation over a **fixed number of timeslots**
- Each **option installation bay** has its **own capacity**
- **Minimise** the number of **options not placed** on the production line
- This problem was used in the original **Propagation Guided** paper

Options	Model A	Model B	Model C	Model D
<i>Cruise Control</i>	✓	✗	✓	✗
<i>Smart phone integration</i>	✗	✓	✓	✓
<i>Air Conditioning</i>	✓	✗	✗	✓
<i>Automatic transmission</i>	✗	✓	✗	✓
<i>Panoramic Roof</i>	✗	✓	✓	✗
<b>Number of cars required:</b>	<b>30</b>	<b>30</b>	<b>20</b>	<b>40</b>



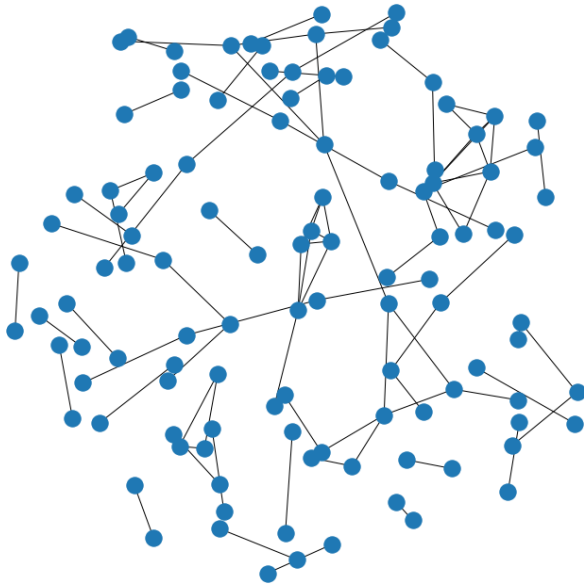
# Machine Reassignment Problem (MRP)

- Proposed by Google in 2012
- Given a **current assignment of processes to machines** in a data centre
- The goal is to **reassign** some of those **processes** in order to:
  - Improve the **machines usage**
  - Minimise the **overload risks**
  - Minimise the **number** of changes
  - Minimise the **complexity** of changes
- Subject to a set of constraint:
  - Capacity
  - Conflict
  - Spread
  - Dependency
  - Transient Usage

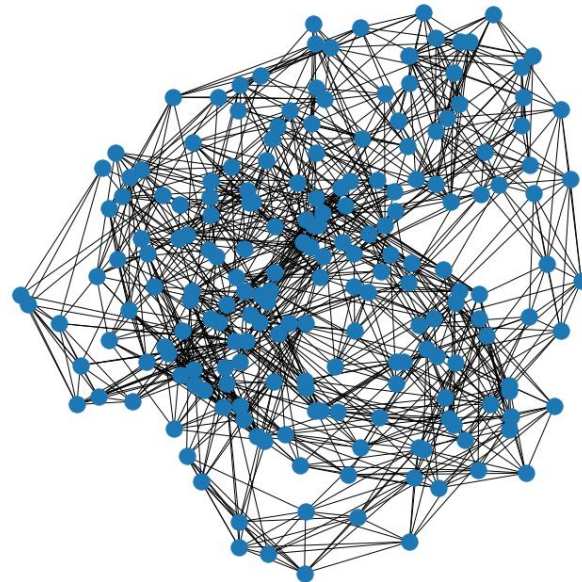


# Structural Relationship

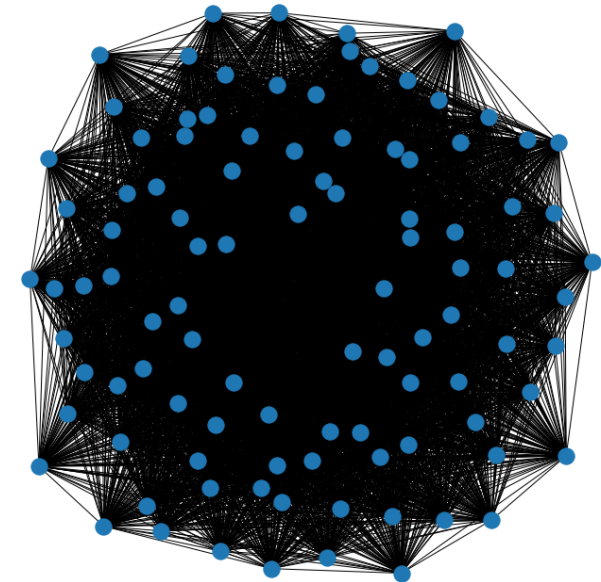
## Steel Mill Slab Problem



## Car Sequencing Problem



## Machine Reassignment Problem



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# Datasets

140 Instances

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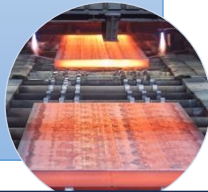
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# Datasets

- Slabs size 2
  - Domain/Variables: 111
- Slabs size 3
  - Domain/Variables: 111
- Slabs size 4
  - Domain/Variables: 111
- Slabs size 5
  - Domain/Variables: 111

80 SMSP



140 Instances

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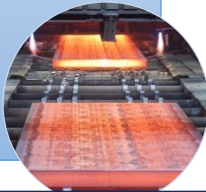
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80 SMSP



- 200 Cars:
  - Domain/Variables: 200
- 300 cars:
  - Domain/Variables: 300
- 400 cars:
  - Domain/Variables: 400

30 CSP



140 Instances

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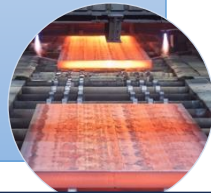
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80 SMSP



- 200 Cars:
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30 CSP



- Set A:
  - Domain: Up to 100
  - Variables: Up to 1000
- Set B:
  - Variables: Up to 50,000
  - Domain: Up to 5,000
- Set X:
  - Variables: Up to 50,000
  - Domain: Up to 5,000

30 MRP



140 Instances

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# Metrics

## Score

- The same metric used in the **ROADEF EURO Challenge 2012**
- Measures the **distance** the solution found is **from** the **BK**
- **Considers** how much **improvement** was made **from** the **initial solution**

$$((Cost - BK) / initialCost) * 100$$

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## Similarity

- The **average** percentage of **intersection** observed across the first **1,000 iterations** of the LNS

$$Similarity = \frac{1}{\binom{1000}{2}} \sum_{i=0}^{999} \sum_{j=i+1}^{999} \frac{|N[i] \cap N[j]|}{|N[i]|}$$

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# Experiments

- Comparison of generic heuristics:
  - **Rand** - Pure random neighbourhood selection
  - **PG** - Interleaved PG-LNS, Reverse PG-LNS, Rand
  - **CIG** - Cost-Impact Guided
  - **iVRG** - Improved Variable Relationship Guided

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# Benchmark

Problem	Group	Score				Similarity				#Iterations (x1000)			
		Rand	PG	CIG	iVRG	Rand	PG	CIG	iVRG	Rand	PG	CIG	iVRG
SMSP	2	10.23%	10.24%	10.79%	<b>5.51%</b>	<b>9.01%</b>	10.10%	9.62%	10.24%	1.7	1.7	1.6	<b>4.4</b>
	3	10.80%	11.81%	11.59%	<b>5.17%</b>	<b>9.01%</b>	10.06%	9.76%	10.26%	2.0	1.9	1.9	<b>4.3</b>
	4	5.51%	5.97%	5.68%	<b>2.81%</b>	<b>9.01%</b>	10.11%	9.85%	10.12%	2.3	2.3	2.3	<b>7.6</b>
	5	4.78%	5.57%	4.58%	<b>2.13%</b>	<b>9.01%</b>	10.17%	10.05%	10.08%	2.7	2.7	2.6	<b>7.6</b>
	<b>Overall</b>	7.83%	8.40%	8.16%	<b>3.91%</b>	<b>9.01%</b>	10.11%	9.82%	10.17%	2.2	2.1	2.1	<b>6.0</b>
CSP	200	9.71%	5.36%	8.97%	<b>4.43%</b>	<b>5.00%</b>	5.01%	5.26%	5.51%	78.2	12.7	<b>131.7</b>	18.4
	300	10.36%	5.46%	9.57%	<b>3.83%</b>	<b>3.33%</b>	3.34%	3.44%	3.64%	52.4	9.1	<b>87.3</b>	12.8
	400	11.58%	5.67%	10.11%	<b>3.86%</b>	2.50%	<b>2.50%</b>	2.55%	2.72%	32.9	6.3	<b>55.5</b>	9.1
	<b>Overall</b>	10.55%	5.50%	9.55%	<b>4.04%</b>	<b>3.61%</b>	3.61%	3.75%	3.95%	54.5	9.3	<b>91.5</b>	13.4
MRP	A	3.69%	5.25%	3.17%	<b>2.33%</b>	<b>4.56%</b>	5.11%	8.80%	5.06%	87.3	7.6	<b>98.7</b>	70.1
	B	0.31%	0.94%	0.36%	<b>0.26%</b>	<b>0.26%</b>	0.26%	3.14%	0.35%	<b>52.2</b>	0.8	13.6	44.0
	X	0.46%	0.62%	0.41%	<b>0.34%</b>	0.29%	<b>0.25%</b>	3.69%	0.38%	<b>53.9</b>	0.8	15.7	34.9
	<b>Overall</b>	1.49%	2.27%	1.31%	<b>0.98%</b>	<b>1.70%</b>	1.87%	5.21%	1.93%	<b>64.5</b>	3.0	42.7	49.7

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	5	4.78%	5.57%	4.58%	<b>2.13%</b>	<b>9.01%</b>	10.17%	10.05%	10.08%	2.7	2.7	2.6	<b>7.6</b>
	<b>Overall</b>	7.83%	8.40%	8.16%	<b>3.91%</b>	<b>9.01%</b>	10.11%	9.82%	10.17%	2.2	2.1	2.1	<b>6.0</b>
CSP	200	9.71%	5.36%	8.97%	<b>4.43%</b>	<b>5.00%</b>	5.01%	5.26%	5.51%	78.2	12.7	<b>131.7</b>	18.4
	300	10.36%	5.46%	9.57%	<b>3.83%</b>	<b>3.33%</b>	3.34%	3.44%	3.64%	52.4	9.1	<b>87.3</b>	12.8
	400	11.58%	5.67%	10.11%	<b>3.86%</b>	2.50%	<b>2.50%</b>	2.55%	2.72%	32.9	6.3	<b>55.5</b>	9.1
	<b>Overall</b>	10.55%	5.50%	9.55%	<b>4.04%</b>	<b>3.61%</b>	3.61%	3.75%	3.95%	54.5	9.3	<b>91.5</b>	13.4
MRP	A	3.69%	5.25%	3.17%	<b>2.33%</b>	<b>4.56%</b>	5.11%	8.80%	5.06%	87.3	7.6	<b>98.7</b>	70.1
	B	0.31%	0.94%	0.36%	<b>0.26%</b>	<b>0.26%</b>	0.26%	3.14%	0.35%	<b>52.2</b>	0.8	13.6	44.0
	X	0.46%	0.62%	0.41%	<b>0.34%</b>	0.29%	<b>0.25%</b>	3.69%	0.38%	<b>53.9</b>	0.8	15.7	34.9
	<b>Overall</b>	1.49%	2.27%	1.31%	<b>0.98%</b>	<b>1.70%</b>	1.87%	5.21%	1.93%	<b>64.5</b>	3.0	42.7	49.7

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# Benchmark

Problem	Group	Score				Similarity				#Iterations (x1000)			
		Rand	PG	CIG	iVRG	Rand	PG	CIG	iVRG	Rand	PG	CIG	iVRG
SMSP	2	10.23%	10.24%	10.79%	<b>5.51%</b>	<b>9.01%</b>	10.10%	9.62%	10.24%	1.7	1.7	1.6	<b>4.4</b>
	3	10.80%	11.81%	11.59%	<b>5.17%</b>	<b>9.01%</b>	10.06%	9.76%	10.26%	2.0	1.9	1.9	<b>4.3</b>
	4	5.51%	5.97%	5.68%	<b>2.81%</b>	<b>9.01%</b>	10.11%	9.85%	10.12%	2.3	2.3	2.3	<b>7.6</b>
	5	4.78%	5.57%	4.58%	<b>2.13%</b>	<b>9.01%</b>	10.17%	10.05%	10.08%	2.7	2.7	2.6	<b>7.6</b>
	<b>Overall</b>	7.83%	8.40%	8.16%	<b>3.91%</b>	<b>9.01%</b>	10.11%	9.82%	10.17%	2.2	2.1	2.1	<b>6.0</b>
CSP	200	9.71%	5.36%	8.97%	<b>4.43%</b>	<b>5.00%</b>	5.01%	5.26%	5.51%	78.2	12.7	<b>131.7</b>	18.4
	300	10.36%	5.46%	9.57%	<b>3.83%</b>	<b>3.33%</b>	3.34%	3.44%	3.64%	52.4	9.1	<b>87.3</b>	12.8
	400	11.58%	5.67%	10.11%	<b>3.86%</b>	2.50%	<b>2.50%</b>	2.55%	2.72%	32.9	6.3	<b>55.5</b>	9.1
	<b>Overall</b>	10.55%	5.50%	9.55%	<b>4.04%</b>	<b>3.61%</b>	3.61%	3.75%	3.95%	54.5	9.3	<b>91.5</b>	13.4
MRP	A	3.69%	5.25%	3.17%	<b>2.33%</b>	<b>4.56%</b>	5.11%	8.80%	5.06%	87.3	7.6	<b>98.7</b>	70.1
	B	0.31%	0.94%	0.36%	<b>0.26%</b>	<b>0.26%</b>	0.26%	3.14%	0.35%	<b>52.2</b>	0.8	13.6	44.0
	X	0.46%	0.62%	0.41%	<b>0.34%</b>	0.29%	<b>0.25%</b>	3.69%	0.38%	<b>53.9</b>	0.8	15.7	34.9
	<b>Overall</b>	1.49%	2.27%	1.31%	<b>0.98%</b>	<b>1.70%</b>	1.87%	5.21%	1.93%	<b>64.5</b>	3.0	42.7	49.7

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# Benchmark

Problem	Group	Score				Similarity				#Iterations (x1000)			
		Rand	PG	CIG	iVRG	Rand	PG	CIG	iVRG	Rand	PG	CIG	iVRG
SMSP	2	10.23%	10.24%	10.79%	<b>5.51%</b>	<b>9.01%</b>	10.10%	9.62%	10.24%	1.7	1.7	1.6	<b>4.4</b>
	3	10.80%	11.81%	11.59%	<b>5.17%</b>	<b>9.01%</b>	10.06%	9.76%	10.26%	2.0	1.9	1.9	<b>4.3</b>
	4	5.51%	5.97%	5.68%	<b>2.81%</b>	<b>9.01%</b>	10.11%	9.85%	10.12%	2.3	2.3	2.3	<b>7.6</b>
	5	4.78%	5.57%	4.58%	<b>2.13%</b>	<b>9.01%</b>	10.17%	10.05%	10.08%	2.7	2.7	2.6	<b>7.6</b>
	<b>Overall</b>	7.83%	8.40%	8.16%	<b>3.91%</b>	<b>9.01%</b>	10.11%	9.82%	10.17%	2.2	2.1	2.1	<b>6.0</b>
CSP	200	9.71%	5.36%	8.97%	<b>4.43%</b>	<b>5.00%</b>	5.01%	5.26%	5.51%	78.2	12.7	<b>131.7</b>	18.4
	300	10.36%	5.46%	9.57%	<b>3.83%</b>	<b>3.33%</b>	3.34%	3.44%	3.64%	52.4	9.1	<b>87.3</b>	12.8
	400	11.58%	5.67%	10.11%	<b>3.86%</b>	2.50%	<b>2.50%</b>	2.55%	2.72%	32.9	6.3	<b>55.5</b>	9.1
	<b>Overall</b>	10.55%	5.50%	9.55%	<b>4.04%</b>	<b>3.61%</b>	3.61%	3.75%	3.95%	54.5	9.3	<b>91.5</b>	13.4
MRP	A	3.69%	5.25%	3.17%	<b>2.33%</b>	<b>4.56%</b>	5.11%	8.80%	5.06%	87.3	7.6	<b>98.7</b>	70.1
	B	0.31%	0.94%	0.36%	<b>0.26%</b>	<b>0.26%</b>	0.26%	3.14%	0.35%	<b>52.2</b>	0.8	13.6	44.0
	X	0.46%	0.62%	0.41%	<b>0.34%</b>	0.29%	<b>0.25%</b>	3.69%	0.38%	<b>53.9</b>	0.8	15.7	34.9
	<b>Overall</b>	1.49%	2.27%	1.31%	<b>0.98%</b>	<b>1.70%</b>	1.87%	5.21%	1.93%	<b>64.5</b>	3.0	42.7	49.7

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# Experiments

- Comparison of generic heuristics:
  - **Rand** - Pure random neighbourhood selection
  - **PG** - Interleaved PG-LNS, Reverse PG-LNS, Rand
  - **CIG** - Cost-Impact Guided
  - **iVRG** - Improved Variable Relationship Guided
- Comparison of iVRG components:
  - **NonT** – iVRG without tournament selection (so chooses amongst all variables)
  - **NonS** – iVRG without using search state information (so chooses randomly amongst tournament of variables related to previous selected)
  - **NonR** – iVRG without variable relationship (so each tournament is just consisting of randomly selected variables, one with best SSI chosen)

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# iVRG Components

Problem	Group	Score				Similarity				#Iterations (x1000)			
		iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR
SMSP	2	<b>5.51%</b>	6.23%	6.24%	10.38%	10.24%	9.92%	<b>9.82%</b>	22.42%	<b>4.4</b>	4.3	4.1	1.8
	3	5.17%	<b>4.93%</b>	5.34%	14.41%	10.26%	10.03%	<b>9.96%</b>	21.57%	4.3	<b>4.5</b>	4.4	2.1
	4	2.81%	<b>2.79%</b>	2.82%	13.68%	10.12%	9.88%	<b>9.85%</b>	21.27%	7.6	7.9	<b>8.0</b>	2.1
	5	2.13%	<b>2.06%</b>	2.28%	17.38%	10.08%	9.90%	<b>9.84%</b>	20.97%	7.6	<b>8.0</b>	7.4	1.9
	<b>Overall</b>	<b>3.91%</b>	4.00%	4.17%	13.96%	10.17%	9.93%	<b>9.87%</b>	21.56%	6.0	<b>6.2</b>	6.0	2.0
CSP	200	<b>4.43%</b>	10.47%	4.50%	9.59%	5.51%	12.57%	<b>5.02%</b>	6.03%	18.4	14.1	14.2	<b>86.8</b>
	300	<b>3.83%</b>	11.11%	4.28%	10.71%	3.64%	10.92%	<b>3.35%</b>	4.02%	12.8	9.7	9.9	<b>56.1</b>
	400	<b>3.86%</b>	9.57%	3.87%	11.32%	2.72%	7.21%	<b>2.50%</b>	3.06%	9.1	6.1	7.4	<b>34.9</b>
	<b>Overall</b>	<b>4.04%</b>	10.38%	4.22%	10.54%	3.95%	10.23%	<b>3.62%</b>	4.37%	13.4	10.0	10.5	<b>59.3</b>
MRP	A	<b>2.33%</b>	6.04%	2.66%	5.85%	5.06%	23.83%	<b>4.75%</b>	10.90%	70.1	65.4	63.1	<b>91.2</b>
	B	<b>0.26%</b>	0.74%	0.29%	0.39%	0.35%	20.10%	<b>0.28%</b>	0.61%	44.0	8.5	44.9	<b>57.0</b>
	X	<b>0.34%</b>	0.90%	0.37%	0.46%	0.38%	20.83%	<b>0.31%</b>	0.67%	34.9	7.2	40.8	<b>89.2</b>
	<b>Overall</b>	<b>0.98%</b>	2.56%	1.11%	2.23%	1.93%	21.59%	<b>1.78%</b>	4.06%	49.7	27.0	49.6	<b>79.1</b>

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# iVRG Components

Problem	Group	Score				Similarity				#Iterations (x1000)			
		iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR
SMSP	2	<b>5.51%</b>	6.23%	6.24%	10.38%	10.24%	9.92%	<b>9.82%</b>	22.42%	<b>4.4</b>	4.3	4.1	1.8
	3	5.17%	<b>4.93%</b>	5.34%	14.41%	10.26%	10.03%	<b>9.96%</b>	21.57%	4.3	<b>4.5</b>	4.4	2.1
	4	2.81%	<b>2.79%</b>	2.82%	13.68%	10.12%	9.88%	<b>9.85%</b>	21.27%	7.6	7.9	<b>8.0</b>	2.1
	5	2.13%	<b>2.06%</b>	2.28%	17.38%	10.08%	9.90%	<b>9.84%</b>	20.97%	7.6	<b>8.0</b>	7.4	1.9
	<b>Overall</b>	<b>3.91%</b>	4.00%	4.17%	13.96%	10.17%	9.93%	<b>9.87%</b>	21.56%	6.0	<b>6.2</b>	6.0	2.0
CSP	200	<b>4.43%</b>	10.47%	4.50%	9.59%	5.51%	12.57%	<b>5.02%</b>	6.03%	18.4	14.1	14.2	<b>86.8</b>
	300	<b>3.83%</b>	11.11%	4.28%	10.71%	3.64%	10.92%	<b>3.35%</b>	4.02%	12.8	9.7	9.9	<b>56.1</b>
	400	<b>3.86%</b>	9.57%	3.87%	11.32%	2.72%	7.21%	<b>2.50%</b>	3.06%	9.1	6.1	7.4	<b>34.9</b>
	<b>Overall</b>	<b>4.04%</b>	10.38%	4.22%	10.54%	3.95%	10.23%	<b>3.62%</b>	4.37%	13.4	10.0	10.5	<b>59.3</b>
MRP	A	<b>2.33%</b>	6.04%	2.66%	5.85%	5.06%	23.83%	<b>4.75%</b>	10.90%	70.1	65.4	63.1	<b>91.2</b>
	B	<b>0.26%</b>	0.74%	0.29%	0.39%	0.35%	20.10%	<b>0.28%</b>	0.61%	44.0	8.5	44.9	<b>57.0</b>
	X	<b>0.34%</b>	0.90%	0.37%	0.46%	0.38%	20.83%	<b>0.31%</b>	0.67%	34.9	7.2	40.8	<b>89.2</b>
	<b>Overall</b>	<b>0.98%</b>	2.56%	1.11%	2.23%	1.93%	21.59%	<b>1.78%</b>	4.06%	49.7	27.0	49.6	<b>79.1</b>

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# iVRG Components

Problem	Group	Score				Similarity				#Iterations (x1000)			
		iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR
SMSP	2	<b>5.51%</b>	6.23%	6.24%	10.38%	10.24%	9.92%	<b>9.82%</b>	<b>22.42%</b>	<b>4.4</b>	4.3	4.1	1.8
	3	5.17%	<b>4.93%</b>	5.34%	14.41%	10.26%	10.03%	<b>9.96%</b>	21.57%	4.3	<b>4.5</b>	4.4	2.1
	4	2.81%	<b>2.79%</b>	2.82%	13.68%	10.12%	9.88%	<b>9.85%</b>	21.27%	7.6	7.9	<b>8.0</b>	2.1
	5	2.13%	<b>2.06%</b>	2.28%	17.38%	10.08%	9.90%	<b>9.84%</b>	20.97%	7.6	<b>8.0</b>	7.4	1.9
	<b>Overall</b>	<b>3.91%</b>	4.00%	4.17%	13.96%	10.17%	9.93%	<b>9.87%</b>	21.56%	6.0	<b>6.2</b>	6.0	2.0
CSP	200	<b>4.43%</b>	10.47%	4.50%	9.59%	5.51%	12.57%	<b>5.02%</b>	6.03%	18.4	14.1	14.2	<b>86.8</b>
	300	<b>3.83%</b>	11.11%	4.28%	10.71%	3.64%	10.92%	<b>3.35%</b>	4.02%	12.8	9.7	9.9	<b>56.1</b>
	400	<b>3.86%</b>	9.57%	3.87%	11.32%	2.72%	7.21%	<b>2.50%</b>	3.06%	9.1	6.1	7.4	<b>34.9</b>
	<b>Overall</b>	<b>4.04%</b>	10.38%	4.22%	10.54%	3.95%	10.23%	<b>3.62%</b>	4.37%	13.4	10.0	10.5	<b>59.3</b>
MRP	A	<b>2.33%</b>	6.04%	2.66%	5.85%	5.06%	23.83%	<b>4.75%</b>	10.90%	70.1	65.4	63.1	<b>91.2</b>
	B	<b>0.26%</b>	0.74%	0.29%	0.39%	0.35%	20.10%	<b>0.28%</b>	0.61%	44.0	8.5	44.9	<b>57.0</b>
	X	<b>0.34%</b>	0.90%	0.37%	0.46%	0.38%	20.83%	<b>0.31%</b>	0.67%	34.9	7.2	40.8	<b>89.2</b>
	<b>Overall</b>	<b>0.98%</b>	2.56%	1.11%	2.23%	1.93%	21.59%	<b>1.78%</b>	4.06%	49.7	27.0	49.6	<b>79.1</b>

# iVRG Components

Problem	Group	Score				Similarity				#Iterations (x1000)			
		iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR
SMSP	2	<b>5.51%</b>	6.23%	6.24%	10.38%	10.24%	9.92%	<b>9.82%</b>	22.42%	<b>4.4</b>	4.3	4.1	1.8
	3	5.17%	<b>4.93%</b>	5.34%	14.41%	10.26%	10.03%	<b>9.96%</b>	21.57%	4.3	<b>4.5</b>	4.4	2.1
	4	2.81%	<b>2.79%</b>	2.82%	13.68%	10.12%	9.88%	<b>9.85%</b>	21.27%	7.6	7.9	<b>8.0</b>	2.1
	5	2.13%	<b>2.06%</b>	2.28%	17.38%	10.08%	9.90%	<b>9.84%</b>	20.97%	7.6	<b>8.0</b>	7.4	1.9
	<b>Overall</b>	<b>3.91%</b>	4.00%	4.17%	13.96%	10.17%	9.93%	<b>9.87%</b>	21.56%	6.0	<b>6.2</b>	6.0	2.0
CSP	200	<b>4.43%</b>	10.47%	4.50%	9.59%	5.51%	12.57%	<b>5.02%</b>	6.03%	18.4	14.1	14.2	<b>86.8</b>
	300	<b>3.83%</b>	11.11%	4.28%	10.71%	3.64%	10.92%	<b>3.35%</b>	4.02%	12.8	9.7	9.9	<b>56.1</b>
	400	<b>3.86%</b>	9.57%	3.87%	11.32%	2.72%	7.21%	<b>2.50%</b>	3.06%	9.1	6.1	7.4	<b>34.9</b>
	<b>Overall</b>	<b>4.04%</b>	10.38%	4.22%	10.54%	3.95%	10.23%	<b>3.62%</b>	4.37%	13.4	10.0	10.5	<b>59.3</b>
MRP	A	<b>2.33%</b>	6.04%	2.66%	5.85%	5.06%	23.83%	<b>4.75%</b>	10.90%	70.1	65.4	63.1	<b>91.2</b>
	B	<b>0.26%</b>	0.74%	0.29%	0.39%	0.35%	20.10%	<b>0.28%</b>	0.61%	44.0	8.5	44.9	<b>57.0</b>
	X	<b>0.34%</b>	0.90%	0.37%	0.46%	0.38%	20.83%	<b>0.31%</b>	0.67%	34.9	7.2	40.8	<b>89.2</b>
	<b>Overall</b>	<b>0.98%</b>	2.56%	1.11%	2.23%	1.93%	21.59%	<b>1.78%</b>	4.06%	49.7	27.0	49.6	<b>79.1</b>

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# iVRG Components

Problem	Group	Score				Similarity				#Iterations (x1000)			
		iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR
SMSP	2	<b>5.51%</b>	6.23%	6.24%	10.38%	10.24%	9.92%	<b>9.82%</b>	22.42%	<b>4.4</b>	4.3	4.1	<b>1.8</b>
	3	5.17%	<b>4.93%</b>	5.34%	14.41%	10.26%	10.03%	<b>9.96%</b>	21.57%	4.3	<b>4.5</b>	4.4	2.1
	4	2.81%	<b>2.79%</b>	2.82%	13.68%	10.12%	9.88%	<b>9.85%</b>	21.27%	7.6	7.9	<b>8.0</b>	2.1
	5	2.13%	<b>2.06%</b>	2.28%	17.38%	10.08%	9.90%	<b>9.84%</b>	20.97%	7.6	<b>8.0</b>	7.4	1.9
	<b>Overall</b>	<b>3.91%</b>	4.00%	4.17%	13.96%	10.17%	9.93%	<b>9.87%</b>	21.56%	6.0	<b>6.2</b>	6.0	<b>2.0</b>
CSP	200	<b>4.43%</b>	10.47%	4.50%	9.59%	5.51%	12.57%	<b>5.02%</b>	6.03%	18.4	14.1	14.2	<b>86.8</b>
	300	<b>3.83%</b>	11.11%	4.28%	10.71%	3.64%	10.92%	<b>3.35%</b>	4.02%	12.8	9.7	9.9	<b>56.1</b>
	400	<b>3.86%</b>	9.57%	3.87%	11.32%	2.72%	7.21%	<b>2.50%</b>	3.06%	9.1	6.1	7.4	<b>34.9</b>
	<b>Overall</b>	<b>4.04%</b>	10.38%	4.22%	10.54%	3.95%	10.23%	<b>3.62%</b>	4.37%	13.4	10.0	10.5	<b>59.3</b>
MRP	A	<b>2.33%</b>	6.04%	2.66%	5.85%	5.06%	23.83%	<b>4.75%</b>	10.90%	70.1	65.4	63.1	<b>91.2</b>
	B	<b>0.26%</b>	0.74%	0.29%	0.39%	0.35%	20.10%	<b>0.28%</b>	0.61%	44.0	8.5	44.9	<b>57.0</b>
	X	<b>0.34%</b>	0.90%	0.37%	0.46%	0.38%	20.83%	<b>0.31%</b>	0.67%	34.9	7.2	40.8	<b>89.2</b>
	<b>Overall</b>	<b>0.98%</b>	2.56%	1.11%	2.23%	1.93%	21.59%	<b>1.78%</b>	4.06%	49.7	27.0	49.6	<b>79.1</b>

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# iVRG Components

Problem	Group	Score				Similarity				#Iterations (x1000)			
		iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR
SMSP	2	<b>5.51%</b>	6.23%	6.24%	10.38%	10.24%	9.92%	<b>9.82%</b>	22.42%	<b>4.4</b>	4.3	4.1	<b>1.8</b>
	3	5.17%	<b>4.93%</b>	5.34%	14.41%	10.26%	10.03%	<b>9.96%</b>	21.57%	4.3	<b>4.5</b>	4.4	2.1
	4	2.81%	<b>2.79%</b>	2.82%	13.68%	10.12%	9.88%	<b>9.85%</b>	21.27%	7.6	7.9	<b>8.0</b>	2.1
	5	2.13%	<b>2.06%</b>	2.28%	17.38%	10.08%	9.90%	<b>9.84%</b>	20.97%	7.6	<b>8.0</b>	7.4	1.9
	<b>Overall</b>	<b>3.91%</b>	4.00%	4.17%	13.96%	10.17%	9.93%	<b>9.87%</b>	21.56%	6.0	<b>6.2</b>	6.0	<b>2.0</b>

Problem	Group	Score				Similarity				#Iterations (x1000)			
		Rand	PG	CIG	iVRG	Rand	PG	CIG	iVRG	Rand	PG	CIG	iVRG
SMSP	2	10.23%	10.24%	10.79%	<b>5.51%</b>	<b>9.01%</b>	10.10%	9.62%	10.24%	<b>1.7</b>	1.7	1.6	<b>4.4</b>
	3	10.80%	11.81%	11.59%	<b>5.17%</b>	<b>9.01%</b>	10.06%	9.76%	10.26%	2.0	1.9	1.9	<b>4.3</b>
	4	5.51%	5.97%	5.68%	<b>2.81%</b>	<b>9.01%</b>	10.11%	9.85%	10.12%	2.3	2.3	2.3	<b>7.6</b>
	5	4.78%	5.57%	4.58%	<b>2.13%</b>	<b>9.01%</b>	10.17%	10.05%	10.08%	2.7	2.7	2.6	<b>7.6</b>
	<b>Overall</b>	<b>7.83%</b>	8.40%	8.16%	<b>3.91%</b>	<b>9.01%</b>	10.11%	9.82%	10.17%	<b>2.2</b>	2.1	2.1	<b>6.0</b>
200	9.71%	5.36%	8.97%	<b>4.43%</b>	<b>5.00%</b>	5.01%	5.26%	5.51%	78.2	12.7	<b>131.7</b>	18.4	

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# iVRG Components

Problem	Group	Score				Similarity				#Iterations (x1000)			
		iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR	iVRG	NonT	NonS	NonR
SMSP	2	<b>5.51%</b>	6.23%	6.24%	10.38%	10.24%	9.92%	<b>9.82%</b>	22.42%	<b>4.4</b>	4.3	4.1	1.8
	3	5.17%	<b>4.93%</b>	5.34%	14.41%	10.26%	10.03%	<b>9.96%</b>	21.57%	4.3	<b>4.5</b>	4.4	2.1
	4	2.81%	<b>2.79%</b>	2.82%	13.68%	10.12%	9.88%	<b>9.85%</b>	21.27%	7.6	7.9	<b>8.0</b>	2.1
	5	2.13%	<b>2.06%</b>	2.28%	17.38%	10.08%	9.90%	<b>9.84%</b>	20.97%	7.6	<b>8.0</b>	7.4	1.9
	<b>Overall</b>	<b>3.91%</b>	4.00%	4.17%	13.96%	10.17%	9.93%	<b>9.87%</b>	21.56%	6.0	<b>6.2</b>	6.0	2.0
CSP	200	<b>4.43%</b>	10.47%	4.50%	9.59%	5.51%	12.57%	<b>5.02%</b>	6.03%	18.4	14.1	14.2	<b>86.8</b>
	300	<b>3.83%</b>	11.11%	4.28%	10.71%	3.64%	10.92%	<b>3.35%</b>	4.02%	12.8	9.7	9.9	<b>56.1</b>
	400	<b>3.86%</b>	9.57%	3.87%	11.32%	2.72%	7.21%	<b>2.50%</b>	3.06%	9.1	6.1	7.4	<b>34.9</b>
	<b>Overall</b>	<b>4.04%</b>	10.38%	4.22%	10.54%	3.95%	10.23%	<b>3.62%</b>	4.37%	13.4	10.0	10.5	<b>59.3</b>
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	<b>Overall</b>	<b>0.98%</b>	2.56%	1.11%	2.23%	1.93%	21.59%	<b>1.78%</b>	4.06%	49.7	27.0	49.6	<b>79.1</b>

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	<b>Overall</b>	<b>0.98%</b>	2.56%	1.11%	2.23%	1.93%	21.59%	<b>1.78%</b>	4.06%	49.7	27.0	49.6	<b>79.1</b>

# Conclusion

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# Conclusion

- Good neighbourhoods can be identified through combining information regarding the **problem structure** with **information collected during search**

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# Conclusion

- Good neighbourhoods can be identified through combining information regarding the **problem structure** with **information collected during search**
- The empirical evaluation demonstrated the **generalisability** of iVRG

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# Conclusion

- Good neighbourhoods can be identified through combining information regarding the **problem structure** with **information collected during search**
- The empirical evaluation demonstrated the **generalisability** of iVRG
- The **structural Relationship** was the most important aspect, followed closely by **tournament selection**.

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