

# CSPs with Few Alien Constraints

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- Motivation
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# Alien Constraints

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$\neq_3 = \{(1, 0), (0, 1), (1, 2), (2, 1), (0, 2), (2, 0)\}$

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$\text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$

Instances contain at most  $k$   $\mathcal{B}$ -constraints

Basic assumption:

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Basic question: What is the largest  $k$  such that  $\text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$  is polynomial-time solvable?

# Motivation

## Motivation I

The polynomial-time solvable fragments of  $\text{CSP}(\mathcal{A})$  are known in many cases.

- Finite domains
- Allen's algebra
- Equality languages
- Temporal relations
- ...

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Quite difficult to work with!

Adding a small number of relations outside  $\mathcal{A}$  can be really helpful  $\rightarrow \text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$

We illustrate this idea with model checking, but there are many other examples. Global constraints (e.g. the all-diff constraint) is one of them.

## Motivation I

Typically, there are two possibilities.

- (1)  $\text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$  is polynomial-time solvable for every fixed  $k$ ,  
or
- (2) there exists a fixed  $k$  such that  $\text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$  is NP-hard.



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Case (2) is almost always bad.

Case (1) is better, and sometimes *much* better.

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Parameterized complexity.

Case (1a)  $\text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$  is *fixed-parameter tractable* (FPT) with parameter  $k$ .

Case (1b)  $\text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$  is in XP.

Case (2)  $\text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$  is pNP-hard.

## Motivation II

Redundant( $\mathcal{A}$ )

"Can one remove constraint  $c$  without changing the set of solutions?"

Impl( $\mathcal{A}$ )

"Is the set of solutions to  $I_1$  a subset of the solutions to  $I_2$ ?"

Equiv( $\mathcal{A}$ )

"Do  $I_1$  and  $I_2$  have the same set of solutions?"

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Many applications are described in the literature.

Complexity classifications are known in special cases (e.g. Boolean domains).

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We show that the complexity of them can be described in terms of  $\text{CSP}_{\leq 1}(\mathcal{A} \cup \mathcal{B})$  for suitably chosen  $\mathcal{B}$ .

## Motivation III

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The computational complexity of such constraints is known.

$\text{CSP}(\mathcal{A} \vee \mathcal{B}^*)$  is in P

if and only if

- (1)  $\mathcal{A}$  and  $\mathcal{B}$  satisfy an algebraic condition (*1-independence*) and
- (2)  $\text{CSP}_{\leq 1}(\mathcal{A} \cup \mathcal{B})$  is in P.

# Finite-domain CSPs

**Theorem.** Let  $\mathcal{A}, \mathcal{B}$  be constraint languages over a finite domain  $A$ . Then,  $\text{CSP}_{\leq}(\mathcal{A} \cup \mathcal{B})$  is either in FPT or pNP-hard.

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The proof is based on ideas from the universal-algebraic approach to CSPs.

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Warning: This does not imply that  $\text{CSP}_{\leq 1}(\mathcal{A} \cup \mathcal{B})$  is NP-hard whenever  $\text{CSP}_{\leq}(\mathcal{A} \cup \mathcal{B})$  is pNP-hard.

Thus, we cannot say much about problems such as  $\text{Redundant}(\mathcal{A})$ ,  $\text{Impl}(\mathcal{A})$ , and  $\text{Equiv}(\mathcal{A})$ .

**Theorem.** Let  $\mathcal{A}, \mathcal{B}$  be constraint languages over the two-element domain  $\{0, 1\}$ . Assume  $\text{CSP}(\mathcal{A})$  is polynomial-time solvable and  $\text{CSP}(\mathcal{A} \cup \mathcal{B})$  is NP-hard. Then the following hold.

- (1) If  $\mathcal{A}$  is Schaefer, then  $\text{CSP}_{\leq}(\mathcal{A} \cup \mathcal{B})$  is in FPT.
- (2) If (i)  $\mathcal{A}$  is not Schaefer, (ii)  $\mathcal{A}$  is both 0- and 1-valid, (iii)  $\mathcal{B}$  contains a 0/1-pair, and (iv)  $\mathcal{B}$  is 0- or 1-valid, then  $\text{CSP}_{\leq 2}(\mathcal{A} \cup \mathcal{B})$  is NP-hard and  $\text{CSP}_{\leq 1}(\mathcal{A} \cup \mathcal{B})$  is polynomial-time solvable.
- (3) Otherwise,  $\text{CSP}_{\leq 2}(\mathcal{A} \cup \mathcal{B})$  is NP-hard.

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- (3) Otherwise,  $\text{CSP}_{\leq 2}(\mathcal{A} \cup \mathcal{B})$  is NP-hard.

The proof is based on a Schaefer-like analysis of the relations (not so much algebra).

**Corollary.** Let  $\mathcal{A}$  be a language over a two-element domain. Then  $\text{Redundant}(\mathcal{A})$ ,  $\text{Impl}(\mathcal{A})$ , and  $\text{Equiv}(\mathcal{A})$  are either polynomial-time solvable or NP-hard.



# Equality Languages

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$$S(x, y, z) \equiv (x = y \vee x \neq z) \wedge (y = z \vee x \neq y)$$

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The complexity of  $\text{CSP}(\mathcal{A})$  is known for all equality languages  $\mathcal{A}$ .

The complexity of equality languages is a necessary ingredient in *all* classifications of more expressive classes.

Thus, natural to study  $\text{CSP}_{\leq k}(\mathcal{A} \cup \mathcal{B})$  for equality languages  $\mathcal{A}, \mathcal{B}$ .

**Theorem.** Let  $\mathcal{A}, \mathcal{B}$  be equality languages such that  $\text{CSP}(\mathcal{A})$  is polynomial-time solvable and  $\text{CSP}(\mathcal{A} \cup \mathcal{B})$  is NP-hard.

(1) If  $\mathcal{A}$  is Horn,  $\text{CSP}_{\leq}(\mathcal{A} \cup \mathcal{B})$  is in FPT.

(2) If  $\mathcal{A}$  is not Horn,  $\text{CSP}_{\leq}(\mathcal{A} \cup \mathcal{B})$  is pNP-hard. Moreover, there exists an integer  $c = c(\mathcal{A})$  such that  $\text{CSP}_{\leq}(\mathcal{A} \cup \mathcal{B})$  is polynomial-time solvable whenever  $\neq_c \notin \langle \mathcal{A} \cup \mathcal{B} \rangle_{\leq k}$ , and is NP-hard otherwise.

**Theorem.** Let  $\mathcal{A}, \mathcal{B}$  be equality languages such that  $\text{CSP}(\mathcal{A})$  is polynomial-time solvable and  $\text{CSP}(\mathcal{A} \cup \mathcal{B})$  is NP-hard.

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The proof is based on the universal-algebraic approach combined with a recent complexity classification of MinCSP for equality constraints.

**Corollary.** Let  $\mathcal{A}$  be an equality language. Then  $\text{Redundant}(\mathcal{A})$ ,  $\text{Impl}(\mathcal{A})$ , and  $\text{Equiv}(\mathcal{A})$  are either polynomial-time solvable or NP-hard.

# Future Work



Refined classification for finite domains (that covers  $\text{Redundant}(\mathcal{A})$ ,  $\text{Impl}(\mathcal{A})$ , and  $\text{Equiv}(\mathcal{A})$ ).

Classification for other infinite-domain CSPs.

Improved algebraic toolbox for alien constraints.

Are there  $\mathcal{A}$  and  $\mathcal{B}$  such that  $\text{CSP}_{\leq}$  is in XP but not in FPT?

The alien constraints framework is one way of expanding the concept of "tractable CSP". Other ways?