Improved Bounds of Integer Solution Counts via Volume and Extending to Mixed-Integer Linear Constraints

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Outline

- Background
- Our Approach
 - The Framework of Bounds Approximation
 - Sampling Method
 - Extend Bounds to Mixed-Integer Cases
- Evaluation

Linear Constraints

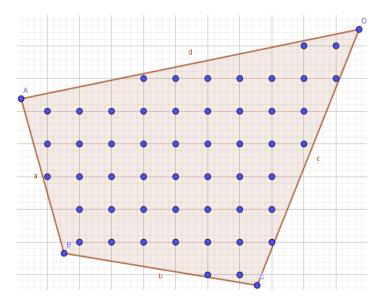
• A LC (linear constraint) is in the form:

 $a_1x_1 + \dots + a_nx_n \text{ op } a_0,$

where x_i are numeric variables, a_i are constants, and $op \in \{<, \le, >, \ge, =\}$.

• A set of LCs is in the form: $A\vec{x} \leq \vec{b}$.

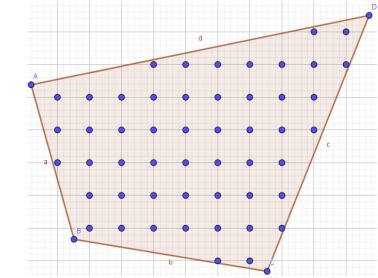
Linear Constraints



- A LC corresponds to a hyperspace.
- A set of LCs corresponds to a convex polytope.

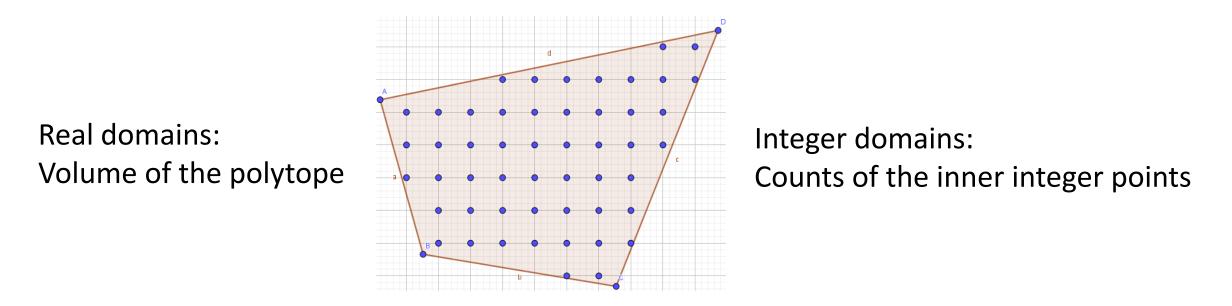
Solution Counting

Real domains: Volume of the polytope



Integer domains: Counts of the inner integer points

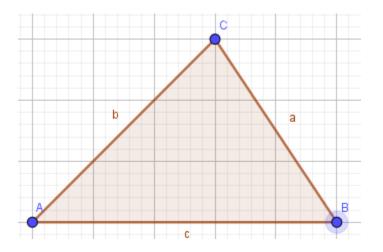
Solution Counting



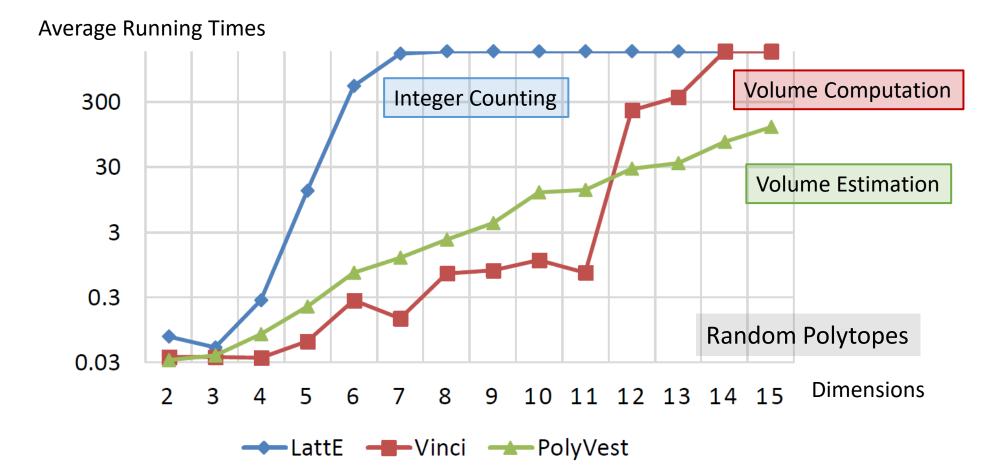
- Let *vol(P)* denote the volume of *P*.
- Let *lat(P)* denote the number of integer points in *P*.

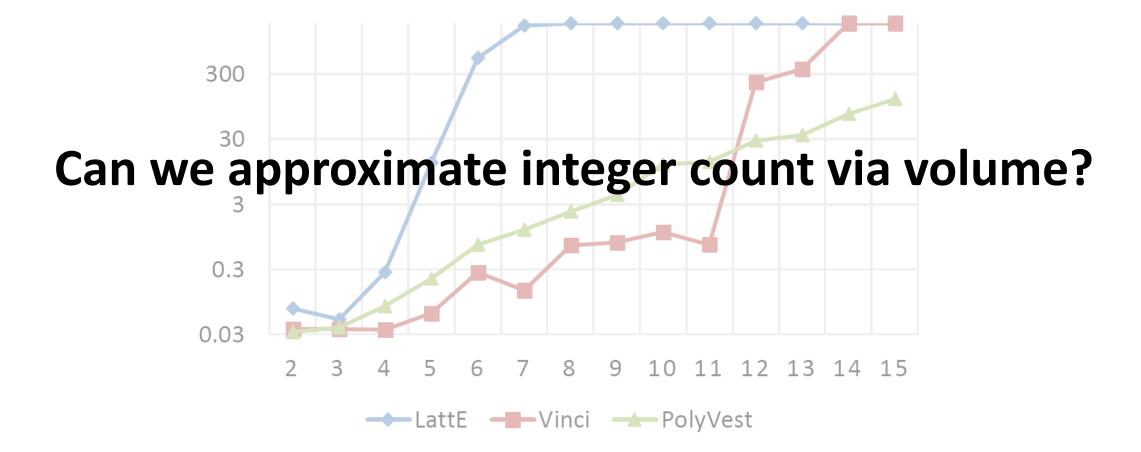
An Example

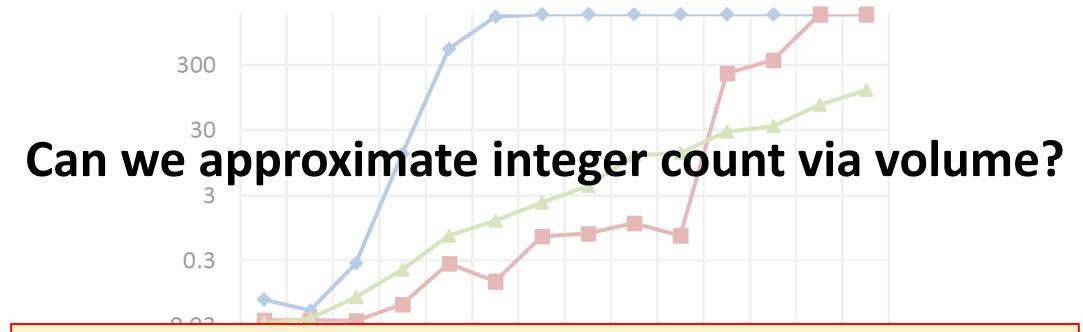
 $(a+b>c) \land (a+c>b) \land (b+c>a) \land$ $(1 \le a \le 32) \land (1 \le b \le 32) \land (1 \le c \le 32).$



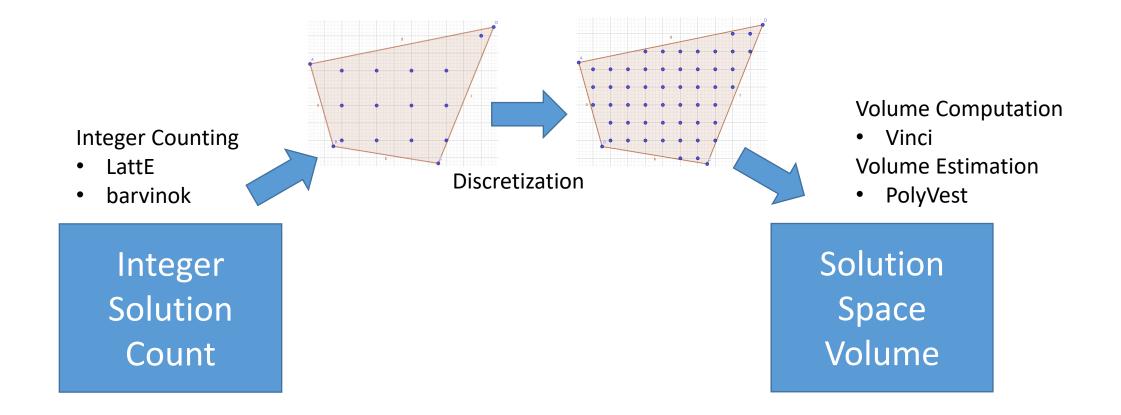
- How many assignments that can form triangles?
 - 16400 integer assignments (integer solutions)
 - Assume a, b, c are reals, then the volume of above formula is $16291 \approx 16400$
- From more experiments, the difference is usually very small.

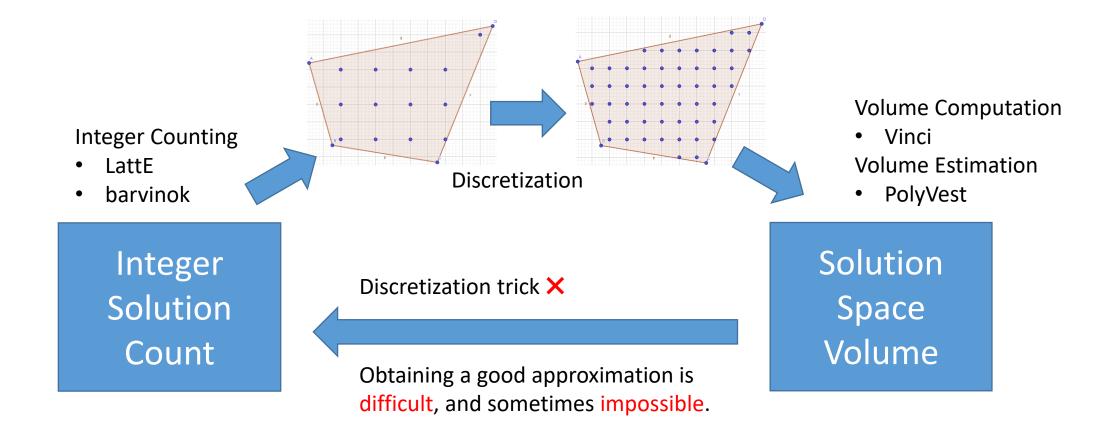


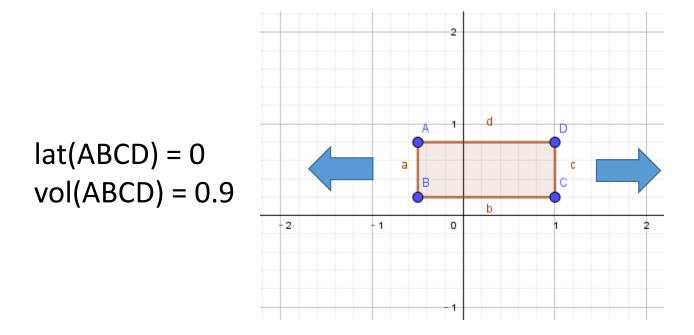




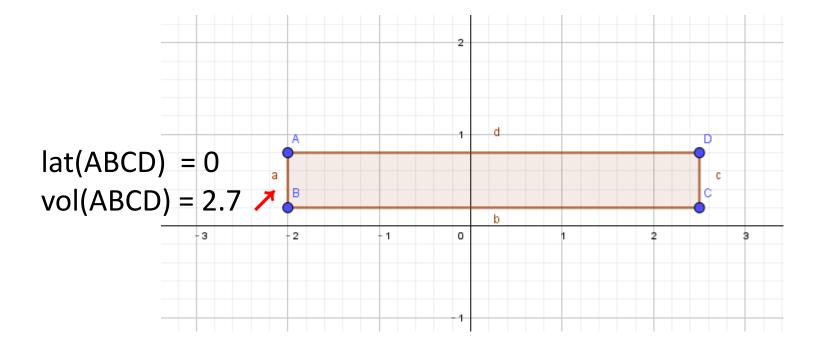
C. Ge, F. Ma, X. Ma, F. Zhang, P. Huang, and J. Zhang. Approximating integer solution counting via space quantification for linear constraints. In Sarit Kraus, editor, Proc. of IJCAI, pages 1697–1703. ijcai.org, 2019. doi:10.24963/ijcai.2019/235.







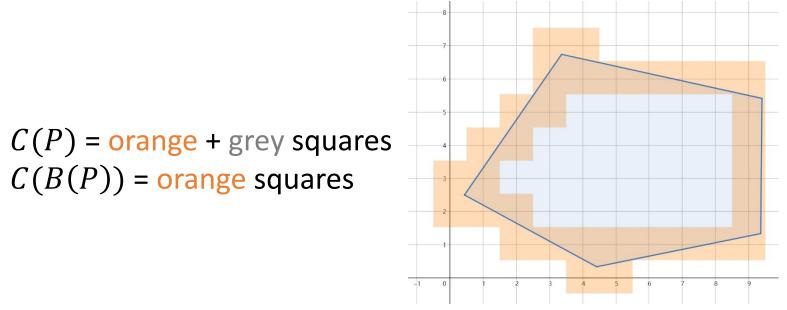
Stretch this "thin" rectangle



Obtaining a good approximation is impossible in this case.

Preliminaries

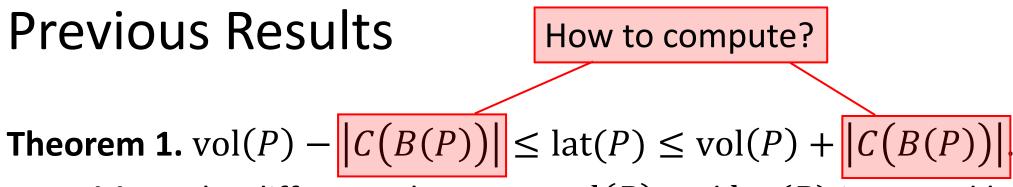
- **Definition:** An **Integer-cube** is a unique unit-cube all of whose centers are integer points.
 - Let C(P) denote the set of integer-cubes which intersect with P.
 - Similarly, we define *C*(*B*(*P*)).



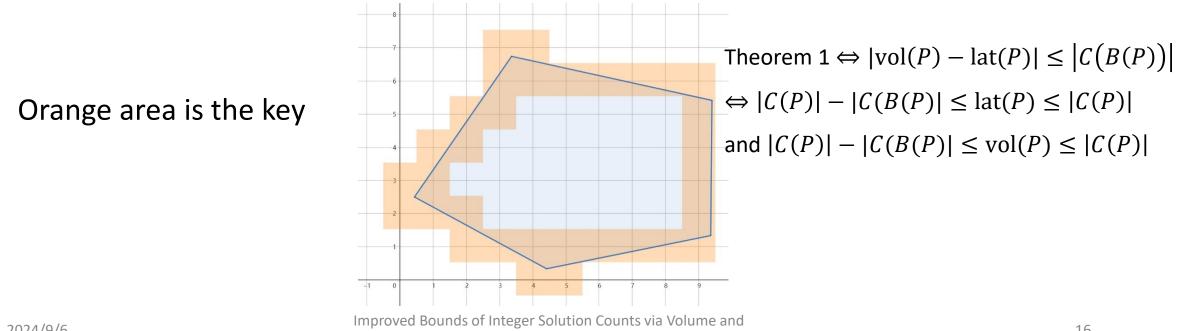
Map each integer-cube to a integer point.

Integer point ↔ Integer-cube

 $\textbf{Count} \leftrightarrow \textbf{Volume}$



• Intuition: The difference between vol(P) and lat(P) is caused by points (integer-cubes) that are close to the boundary of P.



Extending to Mixed-Integer Linear Constraints

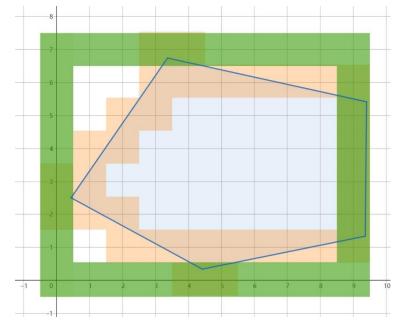
Previous Results

Too loose

Theorem 2.
$$|C(B(P))| \le 2\sum_{i=1}^{n} \prod_{i \ne j} (M_j(P) - m_j(P)),$$

where $m_i(P) = [\min\{x_i | x \in P\} - 1], M_i(P) = [\max\{x_i | x \in P\} + 1].$

Intuition: Mapping orange squares to green squares (cubes close to the surfaces of an outside cuboid).



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Contributions

• A novel algorithm for approximating |C(B(P))|.

- The approximation will be closer to |C(B(P))| than the previous method.
- The guarantee of the approximation is provided and proved.
- Extend Theorem 1 to the mixed-integer cases.

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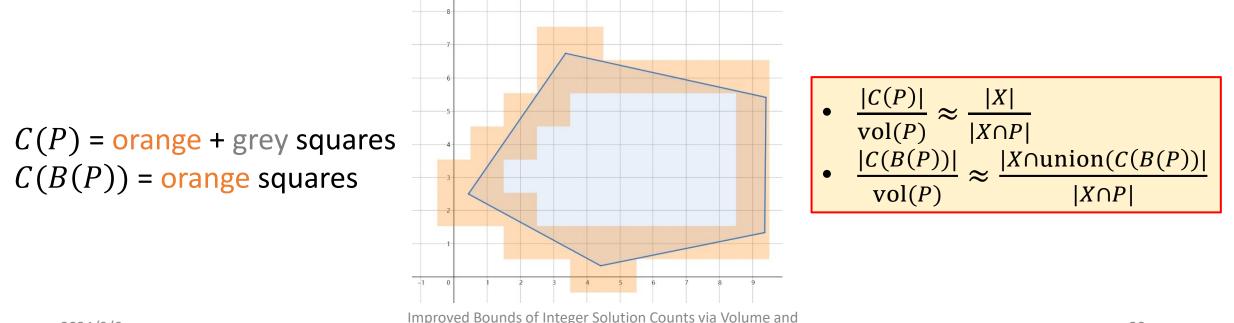
The Framework of Bounds Approximation

The sampling method will be discussed later

• Generate a set of real sample points uniformly in union(C(P)).



• Count the number of samples that lie in *P* and union(C(B(P))), i.e., $|X \cap P|$ and $|X \cap union(C(B(P))|)$. Let *X* denote the set of sample points



The Framework of Bounds Approximation

• Let
$$\hat{r}_1 = \frac{|X|}{|X \cap P|}$$
 and $\hat{r}_2 = 1 - \frac{|X \cap \operatorname{union}(C(BP))|}{|X|}$.

$$= \frac{|C(P)|}{|VOl(P)|} \approx \frac{|X|}{|X \cap P|} = \frac{|X \cap \operatorname{union}(C(B(P)))|}{|VOl(P)|} \approx \frac{|X \cap \operatorname{union}(C(B(P)))|}{|X \cap P|} = \frac{|X \cap \operatorname{union}(C(B(P)))|}{|X \cap P|}$$

1 371

Theorem 3. Given a set of sample points *X* in union(*C*(*P*)). Then $|C(P)| - |C(B(P))| = \operatorname{vol}(P) \cdot \lim_{|X| \to \infty} \frac{\hat{r}_2}{\hat{r}_1}$ and $|C(P)| = \operatorname{vol}(P) \cdot \lim_{|X| \to \infty} \frac{1}{\hat{r}_1}$ Upper bound ub(*P*) of lat(*P*)

The stopping criterion

• Since sampling points is a Bernoulli trial, then \hat{r}_1 and \hat{r}_2 are approximations of proportion of binomial distributions.

The well-known normal approximation confidence interval.

• According to the binomial confidence interval, we know that r_1 lies in interval $\left[\hat{r}_1 - z_{1-\frac{\delta}{4}}\sqrt{\frac{\hat{r}_1(1-\hat{r}_1)}{|X|}}, \hat{r}_1 + z_{1-\frac{\delta}{4}}\sqrt{\frac{\hat{r}_1(1-\hat{r}_1)}{|X|}}\right]$ with probability at least $1 - \delta/2$. Let $\hat{e}_1 = z_{1-\frac{\delta}{4}}\sqrt{\frac{\hat{r}_1(1-\hat{r}_1)}{|X|}}$ and $\hat{e}_2 = z_{1-\frac{\delta}{4}}\sqrt{\frac{\hat{r}_2(1-\hat{r}_2)}{|X|}}$.

The stopping criterion

Recall that
$$\hat{e}_1 = z_{1-\frac{\delta}{4}} \sqrt{\frac{\hat{r}_1(1-\hat{r}_1)}{|X|}}$$
 and $\hat{e}_2 = z_{1-\frac{\delta}{4}} \sqrt{\frac{\hat{r}_2(1-\hat{r}_2)}{|X|}}$.

- r_1 and r_2 lie in interval $[\hat{r}_1 \hat{e}_1, \hat{r}_1 + \hat{e}_1]$ and $[\hat{r}_2 \hat{e}_2, \hat{r}_2 + \hat{e}_2]$ with probability at least $1 \delta/2$, respectively.
- Then $r_1 \ge \hat{r}_1 \hat{e}_1$ and $r_2 \le \hat{r}_2 + \hat{e}_2$ with probability at least $1 \delta/4$.

• Thus
$$\frac{r_2}{r_1} \leq \frac{\hat{r}_2 + \hat{e}_2}{\hat{r}_1 - \hat{e}_1}$$
 with probability at least $1 - \delta/2$.

• Finally,
$$\frac{\hat{r}_2 - \hat{e}_2}{\hat{r}_1 + \hat{e}_1} \leq \frac{r_2}{r_1} \leq \frac{\hat{r}_2 + \hat{e}_2}{\hat{r}_1 - \hat{e}_1}$$
 and $\frac{1}{\hat{r}_1 + \hat{e}_1} \leq \frac{1}{r_1} \leq \frac{1}{\hat{r}_1 - \hat{e}_1}$ with probability $1 - \delta$.

The stopping criterion

Theorem 4. If
$$|X| \ge z_{1-\frac{\delta}{4}}^{2} \cdot \left(\frac{1}{\varepsilon} \cdot \sqrt{\frac{1-r_{2}}{r_{2}}} + \frac{1-\varepsilon}{\varepsilon} \cdot \sqrt{\frac{1-r_{1}}{r_{1}}}\right)^{2}$$
 and $|X| \ge z_{1-\frac{\delta}{4}}^{2} \cdot \left(\frac{1+\varepsilon}{\varepsilon}\right)^{2} \cdot \frac{1-r_{1}}{r_{1}}$, then $\operatorname{Prob}(|\frac{\hat{r}_{2}}{\hat{r}_{1}} - \frac{r_{2}}{r_{1}}| \le \varepsilon \cdot \frac{r_{2}}{\hat{r}_{1}}) \ge 1 - \delta$ and $\operatorname{Prob}(|\frac{1}{\hat{r}_{1}} - \frac{1}{\hat{r}_{1}}| \le \varepsilon \cdot \frac{1}{\hat{r}_{1}}) \ge 1 - \delta$.

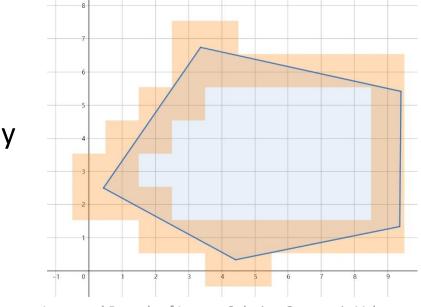
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Q: How to generate sample points nearly uniformly in union(C(P))?

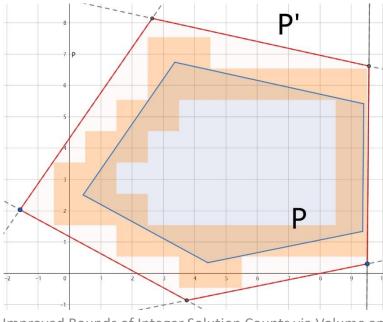
A: Rejection sampling + Nearly uniform sampler on polytopes.

Sampling in orange and grey area (non-convex).

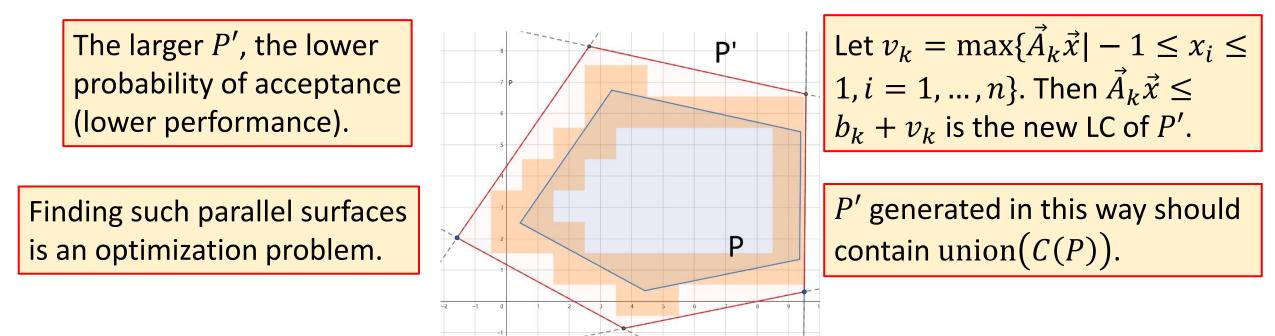


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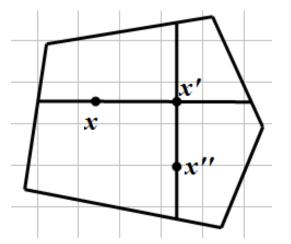
- Step 1: Find a larger polytope P' s.t. union $(C(P)) \subset P'$.
- Step 2: Generate points in P' nearly uniformly.
- Step 3: Reject those points outside union(C(P)).



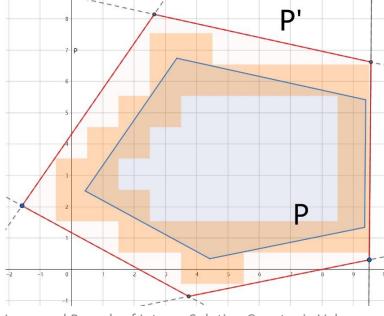
- Step 1: Find a larger polytope P' s.t. union $(C(P)) \subset P'$.
- Shift surfaces of P to obtain P', and P' should as small as possible.



- Step 2: Generate points in P' nearly uniformly.
- Coordinate Directions Hit-and-run method
 - Limiting distribution is uniform.
 - Commonly used in approximating polytopes volume.



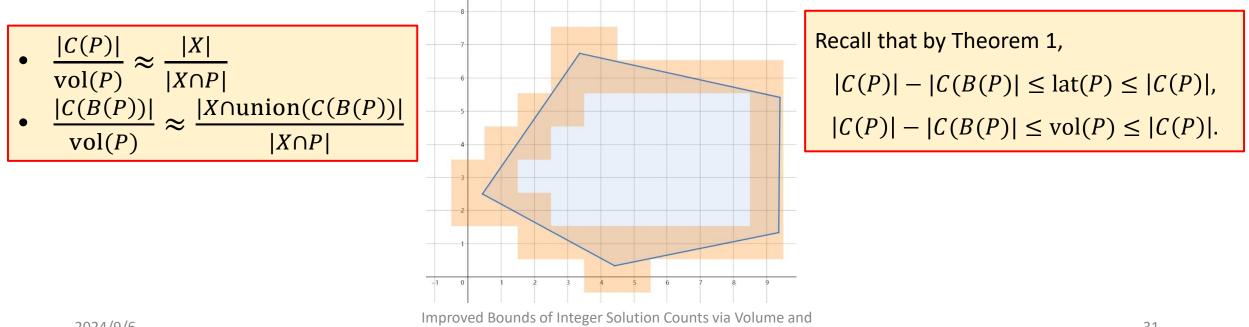
- Step 3: Reject those points outside union(C(P)).
- How to efficiently check whether a point in union(C(P))?



Improved Bounds of Integer Solution Counts via Volume and Extending to Mixed-Integer Linear Constraints

The Framework of Bounds Approximation

- Generate a set of real sample points uniformly in union(C(P)).
- Count the number of samples that lie in P and union(C(B(P))) to approximate |C(P)| and |C(P)| |C(B(P))| eventually.



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- Mixed-Integer Linear Constraints (MILC) are constraints whose variables include not only reals but also integers.
- Without loss of generality, a set of MILCs F can be written in the form $A\vec{x} = A_1\vec{x}_I + A_2\vec{x}_R \le \vec{b}$.

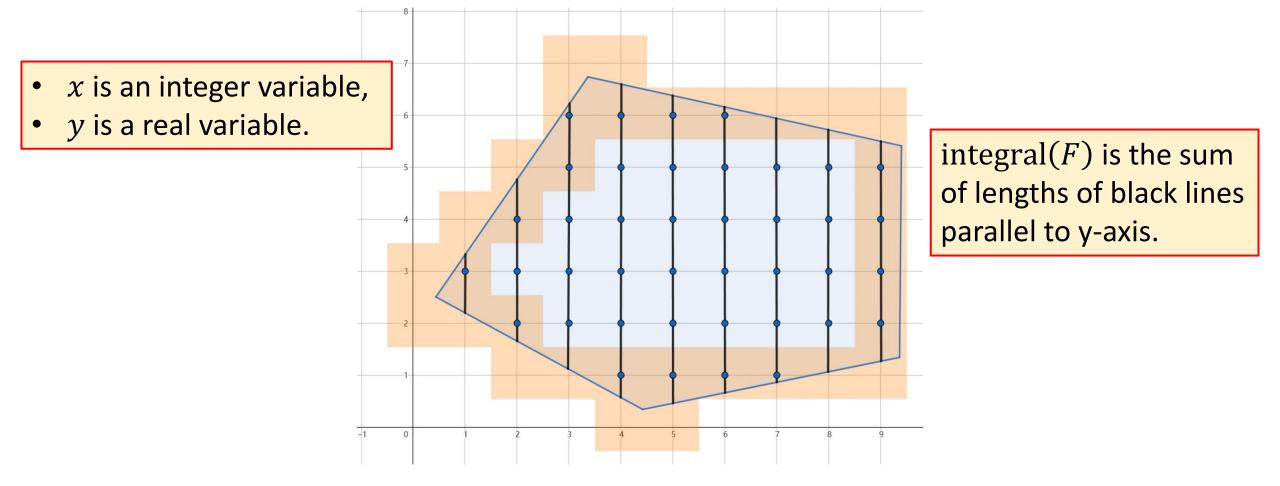
Let
$$n_I = |\vec{x}_I|$$
 and $n_R = |\vec{x}_R|$. Obviously, $n = n_I + n_R$.

• Let integral(*F*) denote the integral on $\mathcal{M}(F)$. In detail integral(*F*) = $\sum_{\vec{\alpha}_I \in \mathcal{M}_I(F)} \operatorname{vol}(F\{\vec{x}_I = \vec{\alpha}_I\})$.

Let $\mathcal{M}(F) = \{\vec{x} \in \mathbb{Z}^{n_I} \times \mathbb{R}^{n_R} : A_1 \vec{x}_I + A_2 \vec{x}_R \leq \vec{b}\}$ denote the solution space of F.

Let $\mathcal{M}_I(F) \subset \mathbb{Z}^{n_I}$ and $\mathcal{M}_R(F) \subset \mathbb{R}^{n_R}$ denote the projection from $\mathcal{M}(F)$ to variables over \vec{x}_I and \vec{x}_R respectively.

Let $F{\vec{x}_I = \vec{\alpha}_I}$ denote the remaining constraints of F by assigning $\vec{\alpha}_I$ to \vec{x}_I .



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Theorem 5. $|C(P)| - |C(B(P)| \le \operatorname{integral}(F) \le |C(P)|.$

It indicates that our algorithm can be directly applied for solving the mixed-integer cases, i.e., $lb(P) \le integral(F) \le ub(P)$.

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Benchmarks

Random Polytopes

- Contains randomly number of integer and real variables.
- The details of generating random polytopes can be found in our paper.

Instances from program analysis

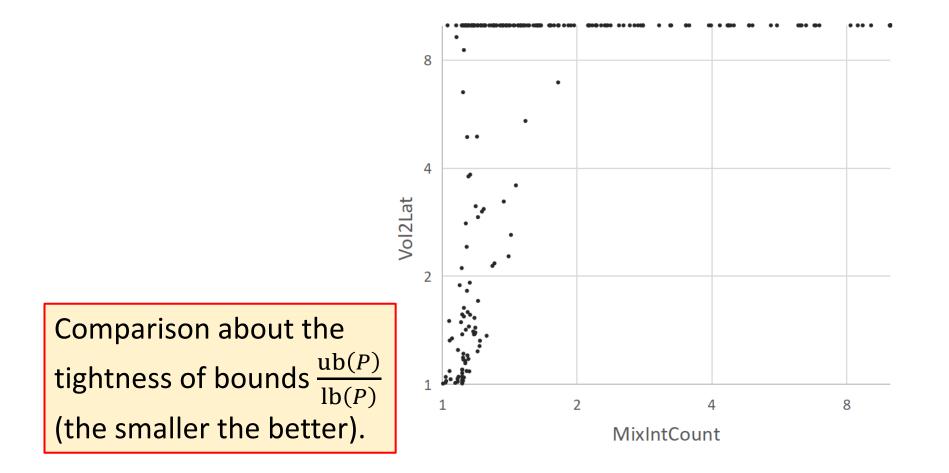
- We adopted the application benchmarks from previous works.
- They were generated by analyzing 7 programs ('cubature', 'gjk', 'http-parser', 'muFFT', 'SimpleXML', 'tcas' and 'timeout') ranging from 0.4k to 7.7k lines of source code via a symbolic execution bug-finding tool.
- There are 3803 SMT(LIA) (linear integer arithmetic) formulas in total.

Benchmarks		rks	ExactMI		Vinci	Vinci		PolyVest		Bounds by MIXINTCOUNT				
n	n_I	$ar{S}$	integral(F)	t (s)	$\mathtt{vol}(P)$	t (s)	$\hat{\texttt{vol}}(P)$	t (s)	$\frac{\operatorname{ub}(P)}{\operatorname{vol}(P)}$	$\frac{\operatorname{lb}(P)}{\operatorname{vol}(P)}$	X	<i>t</i> (s)		
4	1	948	1.44E + 10	4.99	$1.43E{+}10$	0.007	$1.45E{+}10$	0.072	1.055	0.914	281	0.004		
	2	874	6.07E + 08	508	6.07E + 08	0.006	6.15E + 08	0.074	1.172	0.820	1177	0.006		
	3	1099	_		1.47E + 11	0.006	$1.52E{+}11$	0.067	1.037	0.919	156	0.003		
5	1	369	1.64E + 09	1.89	1.64E + 09	0.012	1.66E + 09	0.257	1.479	0.635	2791	0.011		
	2	945	_		8.70E + 12	0.019	$8.59E{+}12$	0.256	1.050	0.935	189	0.005		
	3	1086	_		$6.13E{+}13$	0.018	$6.17E{+}13$	0.249	1.062	0.923	291	0.005		
6	1	715	5.55E + 09	18.3	5.55E + 09	0.053	5.48E + 09	0.755	2.653	0.281	5243	0.023		
	2	1438	_		$1.34E{+}17$	0.067	$1.39E{+}17$	0.780	1.034	0.925	113	0.005		
	3	229	_		5.91E + 09	0.063	5.92E + 09	0.751	1.795	0.464	3824	0.019		
7	1	1101	2.47E + 17	113	$2.47E{+}17$	0.659	$2.50E{+}17$	1.90	1.125	0.848	810	0.008		
	2	980	_		$2.41E{+}17$	0.655	2.44E + 17	2.05	1.136	0.867	855	0.010		
	3	727	_		$6.19E{+}15$	0.658	6.13E + 15	2.04	1.171	0.813	1180	0.011		
8	1	703	$6.57E{+}14$	615	$6.57E{+}14$	7.64	6.44E + 14	4.56	2.036	0.415	4643	0.035		
	2	1251		_	6.83E + 20	7.91	6.83E + 20	4.17	1.099	0.873	628	0.009		
	3	556	Baseline	—	5.71E + 15	8.24	5.68E + 15	4.62	1.695	0.527	3706	0.030		
9	1	475			_		2.37E + 13	9.05	Approximate $lb(P)$ and $ub(P)$, s.t					
	2	1250					3.82E + 22	8.46				ub(P), ba		
12	3	138			lume comp	1.47E + 10	9.71		-	$I(F) \geq 0$	uu(<i>r</i>), ua			
	1	252			approximation		2.56E + 15	57.4	on vol(P)					
	2	439				ation	8.18E+19	54.9	7.063	0.070	45424	0.700		
	3	1408					1.43E + 32	52.3	1.123	0.845	842	0.025		
15	1	958					5.85E + 32	235	2.120	0.408	5102	0.157		
	2	1508		_			$5.10E \pm 38$	228	1.292	0.766	1950	0.076		
rimental results on random polytopes (mixed-integer cases)									1.469	0.635	2902	0.105		

	Benchmarks			ExactMI		Vinci		PolyVest		Bounds by MIXINTCOUNT			
	n	n_I	\bar{S}	integral(F)	t (s)	vol(P)	t (s)	$\hat{vol}(P)$	t (s)	$\frac{\operatorname{ub}(P)}{\operatorname{vol}(P)}$	$\frac{\operatorname{lb}(P)}{\operatorname{vol}(P)}$	X	t (s)
	4	1	948	1.44E + 10	4.99	1.43E + 10	0.007	1.45E + 10	0.072	1.055	0.914	281	0.004
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		3	1099			1.47E + 11	0.006	1.52E + 11	0.067	1.037	0.919	156	0.003
	5	1	369	1.64E + 09	1.89	1.64E + 09	0.012	1.66E + 09	0.257	1.479	0.635	2791	0.011
		2	945			8.70E + 12	0.019	8.59E + 12	0.256	1.050	0.935	189	0.005
		3	1086			6.13E + 13	0.018	6.17E + 13	0.249	1.062	0.923	291	0.005
	6	1	715	5.55E + 09	18.3	5.55E + 09	0.053	5.48E + 09	0.755	2.653	0.281	5243	0.023
		2	1438			1.34E + 17	0.067	$1.39E{+}17$	0.780	1.034	0.925	113	0.005
		3	229			5.91E + 09	0.063	5.92E + 09	0.751	1.795	0.464	3824	0.019
	7	1	1101	2.47E + 17	113	2.47E + 17	0.659	2.50E + 17	1.90	1.125	0.848	810	0.008
		2	980			2.41E + 17	0.655	2.44E + 17	2.05	1.136	0.867	855	0.010
		3	727			6.19E + 15	0.658	$6.13E{+}15$	2.04	1.171	0.813	1180	0.011
	8	1	703	6.57E + 14	615	6.57E + 14	7.64	6.44E + 14	4.56	2.036	0.415	4643	0.035
		2	1251			6.83E + 20	7.91	6.83E + 20	4.17	1.099	0.873	628	0.009
		3	556			5.71E + 15	8.24	5.68E + 15	4.62	1.695	0.527	3706	0.030
	9	1	475					2.37E + 13	9.05	7.560	0.064	49295	0.390
		2	1250				_	3.82E + 22	8.46	1.152	0.836	1016	0.015
•	Bounds are mostly useful.							1.47E + 10	9.71	34.50	0.000	100000	0.792
•	• The overhead is negligible compared to the cost of volume computation or approximation.						2.56E + 15	57.4	43.24	0.001	100000	1.517	
								8.18E + 19	54.9	7.063	0.070	45424	0.700
								1.43E + 32	52.3	1.123	0.845	842	0.025
	15	1	958					5.85E + 32	235	2.120	0.408	5102	0.157
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Expe	xperimental results on random polytopes (mixed-integer cases) 6 224 1.469 0.635 2902 0.10										0.105		

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Experimental results on application instances (pure integer cases)



Thanks!

Homepage: gecunjing.github.io

E-mail: gecunjing@nju.edu.cn

Tools and Benchmarks: <u>https://github.com/bearben/MixIntCount</u>